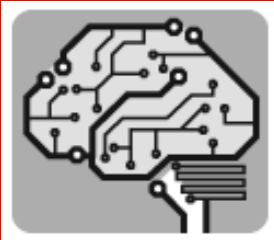


A Basic Machine Learning Kit

Lorenzo Rosasco,

- Università' di Genova

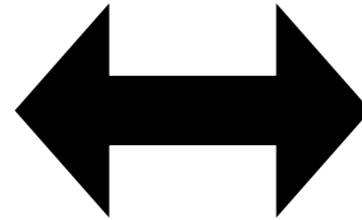
- Istituto Italiano di Tecnologia



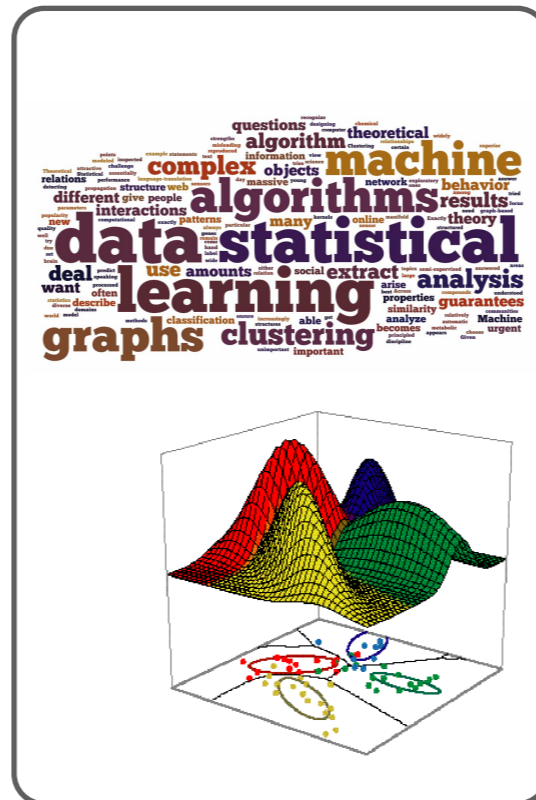
August, 14th 2018 - BMM Summer School, Woods Hole

Machine Learning

Intelligent Systems



Data Science



GOAL: Introduce key algorithms that you can use and complicate when needed



PART I

- Local methods
- Bias-Variance
- Cross Validation

PART II

- Linear Least Squares
- Features and Kernels
- Deep Neural Nets

PART III

- Variable Selection: OMP
- Dimensionality Reduction: PCA

PART IV

- Matlab practical session



Morning

Afternoon

PART I

- Local methods
- Bias-Variance
- Cross Validation

GOAL: Investigate the trade-off between stability and fitting starting from simple machine learning approaches

The goal of supervised learning is to find an underlying input-output relation

$$f(x_{new}) \sim y,$$

given data.

The data, called *training set*, is a set of n input-output pairs,

$$S = \{(x_1, y_1), \dots, (x_n, y_n)\}.$$



170	238	85	255	221	0
68	136	17	170	119	68
221	0	238	136	0	255
119	255	85	170	136	238
238	17	221	68	119	255
85	170	119	221	17	136

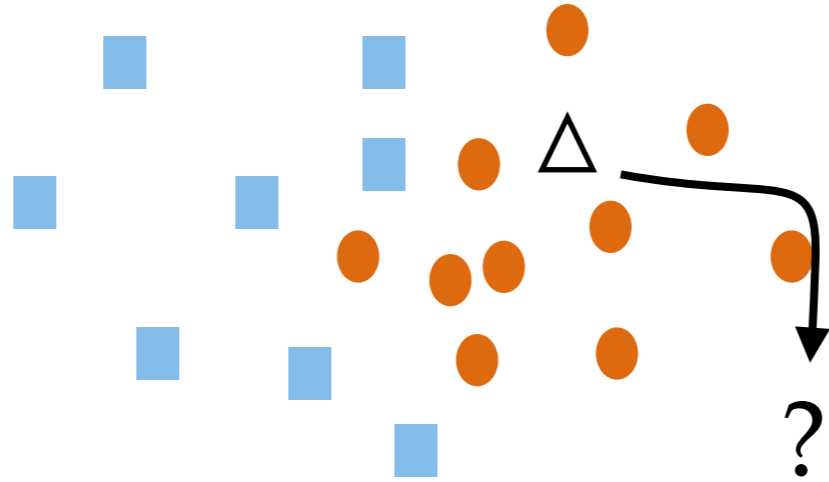
$$X_n = \begin{pmatrix} x_1^1 & \dots & \dots & \dots & x_1^p \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_n^1 & \dots & \dots & \dots & x_n^p \end{pmatrix}$$

$$Y_n = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

+1

-1





Local Methods: Nearby points have similar labels

Nearest Neighbor

Given an input \bar{x} , let

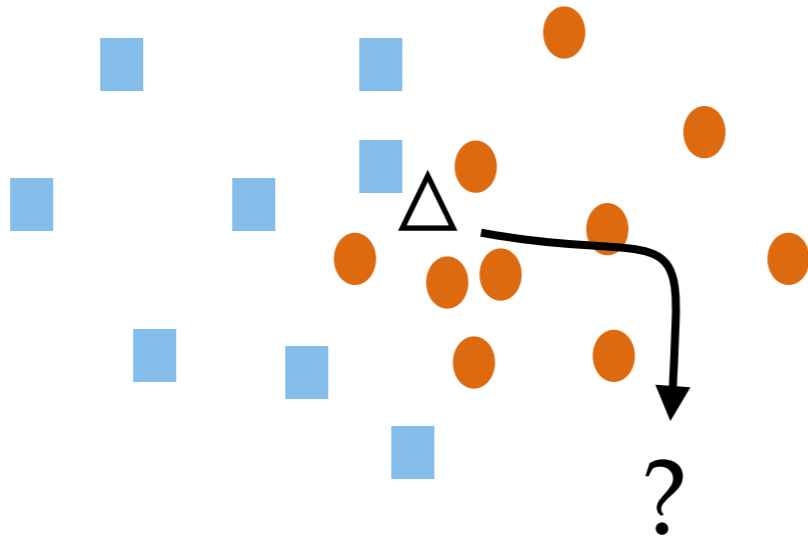
$$i' = \arg \min_{i=1, \dots, n} \|\bar{x} - x_i\|^2$$

and define the nearest neighbor (NN) estimator as

$$\hat{f}(\bar{x}) = y_{i'}.$$

How does it work?

Demo



K-Nearest Neighbors

Consider

$$d_{\bar{x}} = (\| \bar{x} - x_i \|^2)_{i=1}^n$$

the array of distances of a new point \bar{x} to the input points in the training set. Let

$$s_{\bar{x}}$$

be the above array sorted in increasing order and

$$I_{\bar{x}}$$

the corresponding vector of indices, and

$$K_{\bar{x}} = \{I_{\bar{x}}^1, \dots, I_{\bar{x}}^K\}$$

be the array of the first K entries of $I_{\bar{x}}$. The K -nearest neighbor estimator (KNN) is defined as,

$$\hat{f}(\bar{x}) = \sum_{i' \in K_{\bar{x}}} y_{i'}$$

Demo

Remarks:

Generalization I: closer points should count more

$$\hat{f}(\bar{x}) = \frac{\sum_{i=1}^n y_i k(\bar{x}, x_i)}{\sum_{i=1}^n k(\bar{x}, x_i)}, \quad \text{Gaussian } k(x', x) = e^{-\|x-x'\|^2/2\sigma^2}.$$

Parzen Windows

Generalization II: other metric / similarities

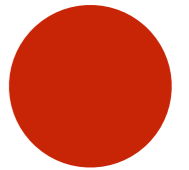
$$X = \{0, 1\}^D \quad d_H(x, \bar{x}) = \frac{1}{D} \sum_{j=1}^D \mathbf{1}_{[x^j \neq \bar{x}^j]}$$

There is one parameter controlling fit/stability

How do we choose it?

Is there an optimal value?

Can we compute it?



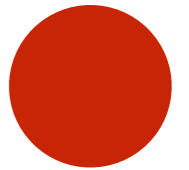
Is there an optimal value?

Ideally we would like to choose K that minimizes the expected error

$$\mathbf{E}_S \mathbf{E}_{x,y} (y - \hat{f}_K(x))^2.$$

Next: Characterize corresponding minimization problem to uncover
one of **the most**
fundamental aspect of machine learning.

For the sake of simplicity we consider a regression model



$$y_i = f_*(x_i) + \delta_i, \quad \mathbf{E}\delta_i = 0, \quad \mathbf{E}\delta_i^2 = \sigma^2 \quad i = 1, \dots, n$$


further let


$$f_K(x) = \mathbf{E}\hat{f}_K(x) = \frac{1}{K} \sum_{\ell \in K_x} f_*(x_\ell)$$

Error decomposition

$$\mathbf{E}(y - \hat{f}_K(x))^2 = \mathbf{E}(y - f_*(x))^2 + \mathbf{E}(f_*(x) - f_K(x))^2 + \mathbf{E}(f_K(x) - \hat{f}_K(x))^2$$


$$\sigma^2$$


$$\mathbf{E}\left(f_*(x) - \frac{1}{K} \sum_{\ell \in K_x} f_*(x_\ell)\right)^2$$


$$\frac{\sigma^2}{Kn}$$

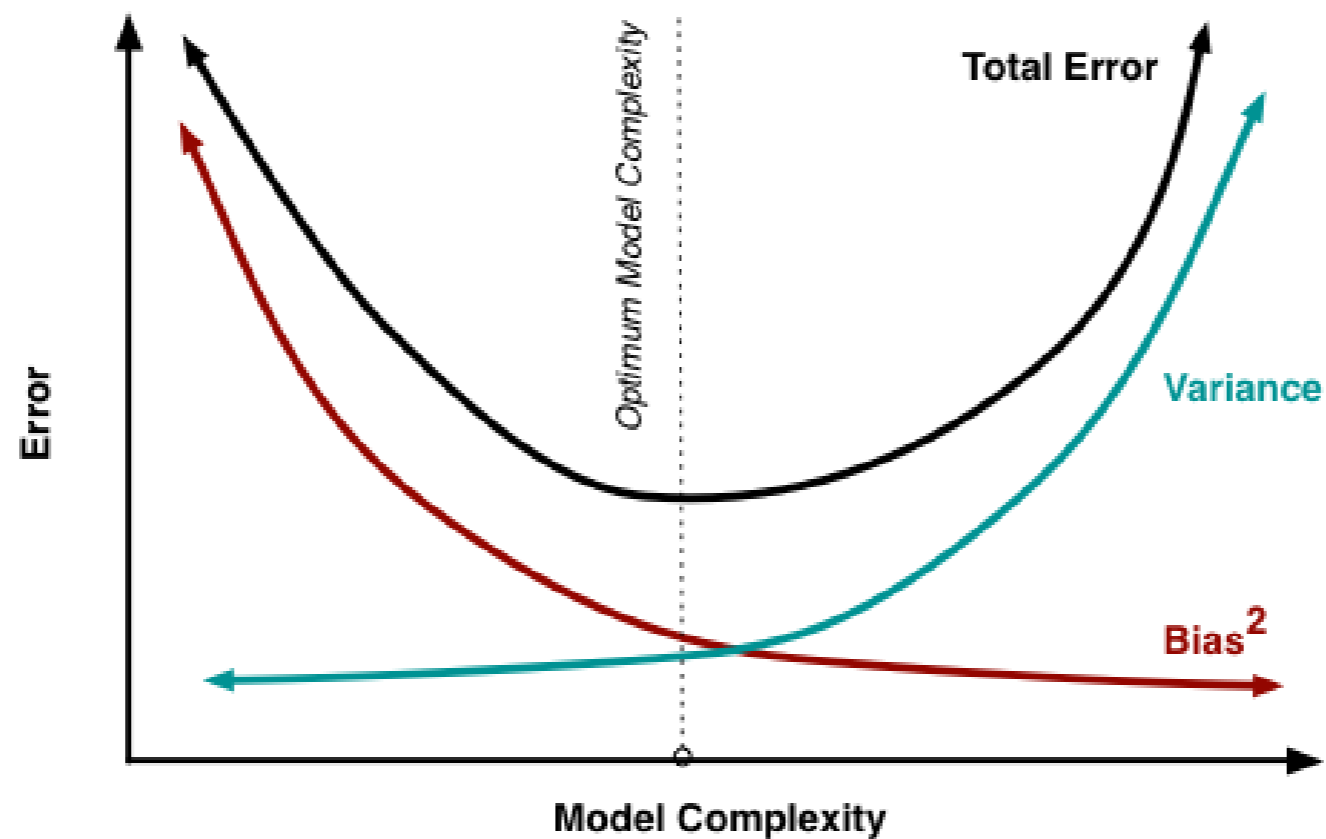
Irreducible error

Bias

Variance

Bias Variance Trade-Off

$$\mathbf{E}(y - \hat{f}_K(x))^2 = \mathbf{E}(y - f_*(x))^2 + \mathbf{E}(f_*(x) - f_K(x))^2 + \mathbf{E}(f_K(x) - \hat{f}_K(x))^2$$



Is there an optimal value? YES!

Can we compute it?

Not quite...

$$\mathbf{E}(y - \hat{f}_K(x))^2 = \mathbf{E}(y - f_*(x))^2 + \mathbf{E}(f_*(x) - f_K(x))^2 + \mathbf{E}(f_K(x) - \hat{f}_K(x))^2$$

$$\sigma^2$$

$$\mathbf{E}\left(f_*(x) - \frac{1}{K} \sum_{\ell \in K_x} f_*(x_\ell)\right)^2$$

$$\frac{\sigma^2}{Kn}$$

Irreducible error

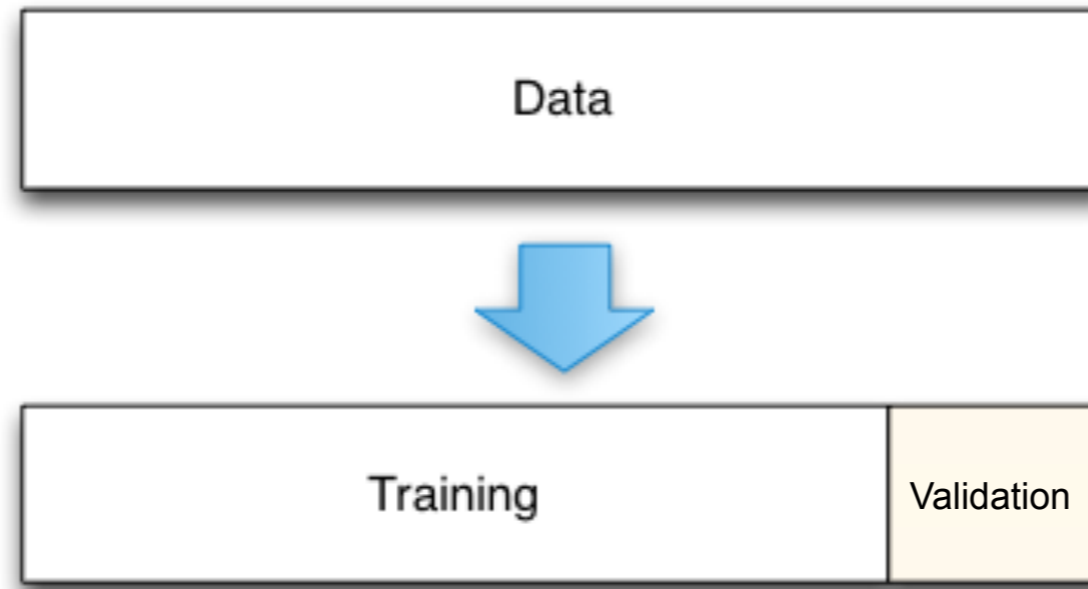
Bias

Variance

...enter Cross Validation

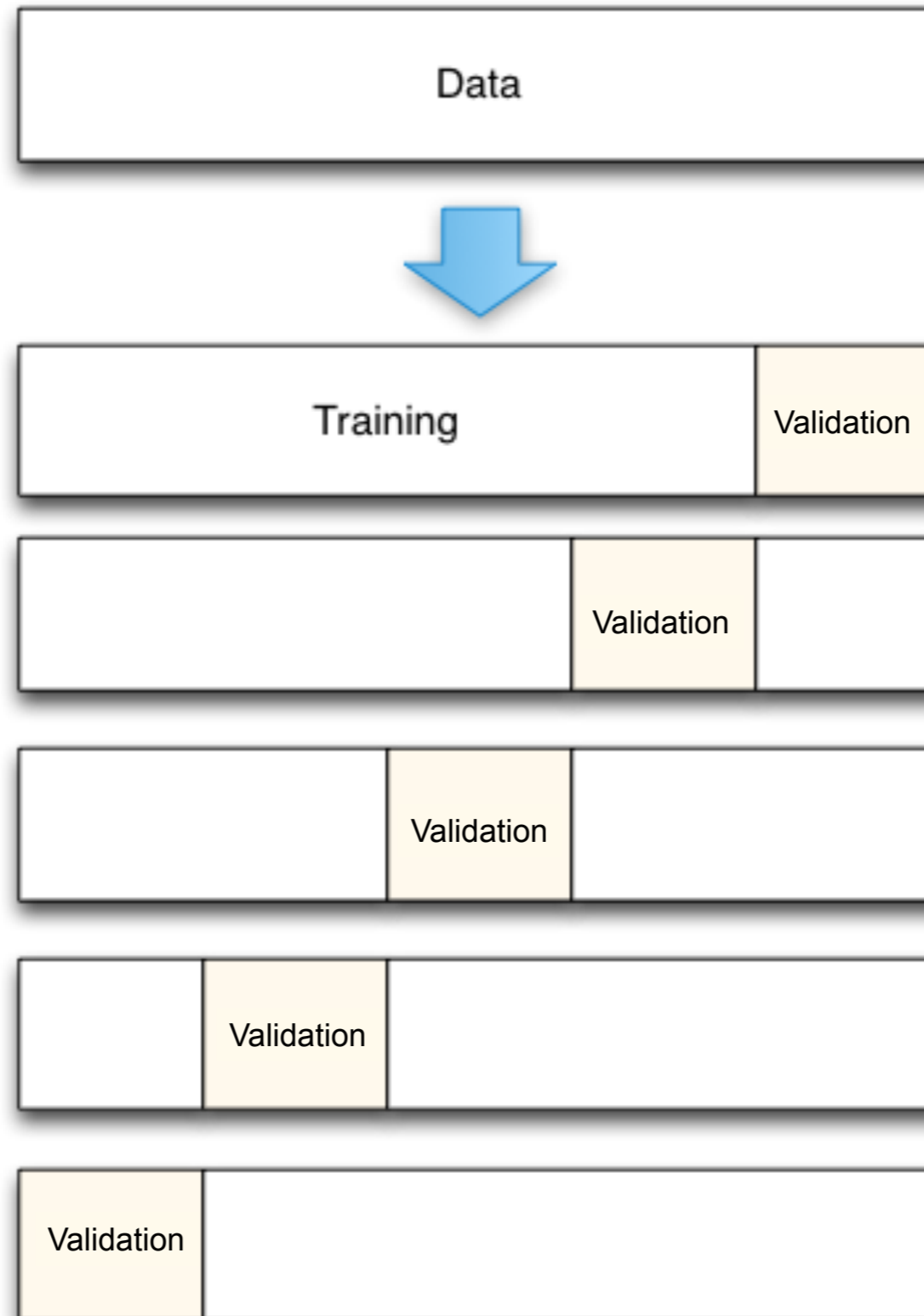
Split data: train on some, tune on some other

Cross Validation Flavors



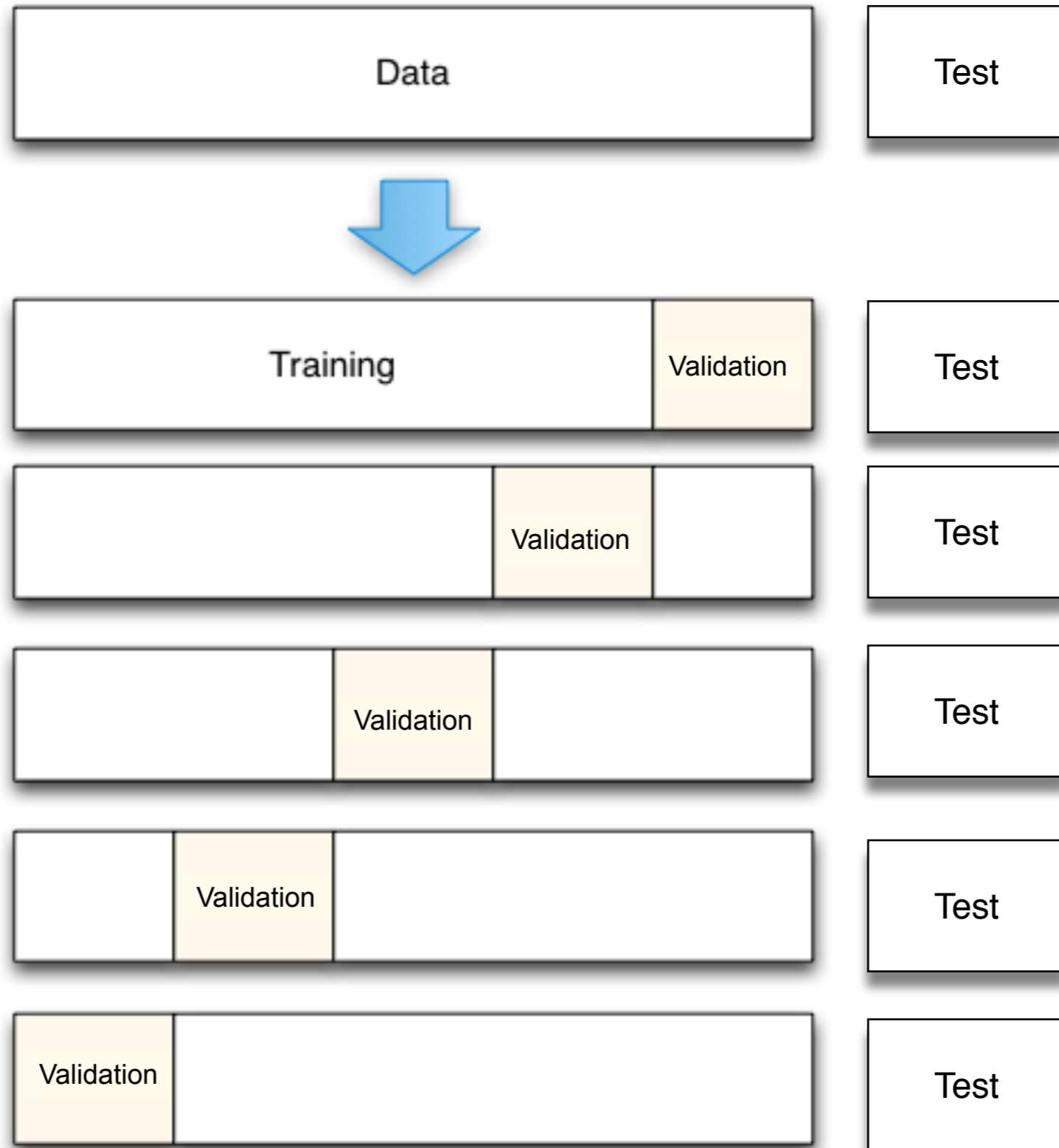
Hold-Out

Cross Validation Flavors



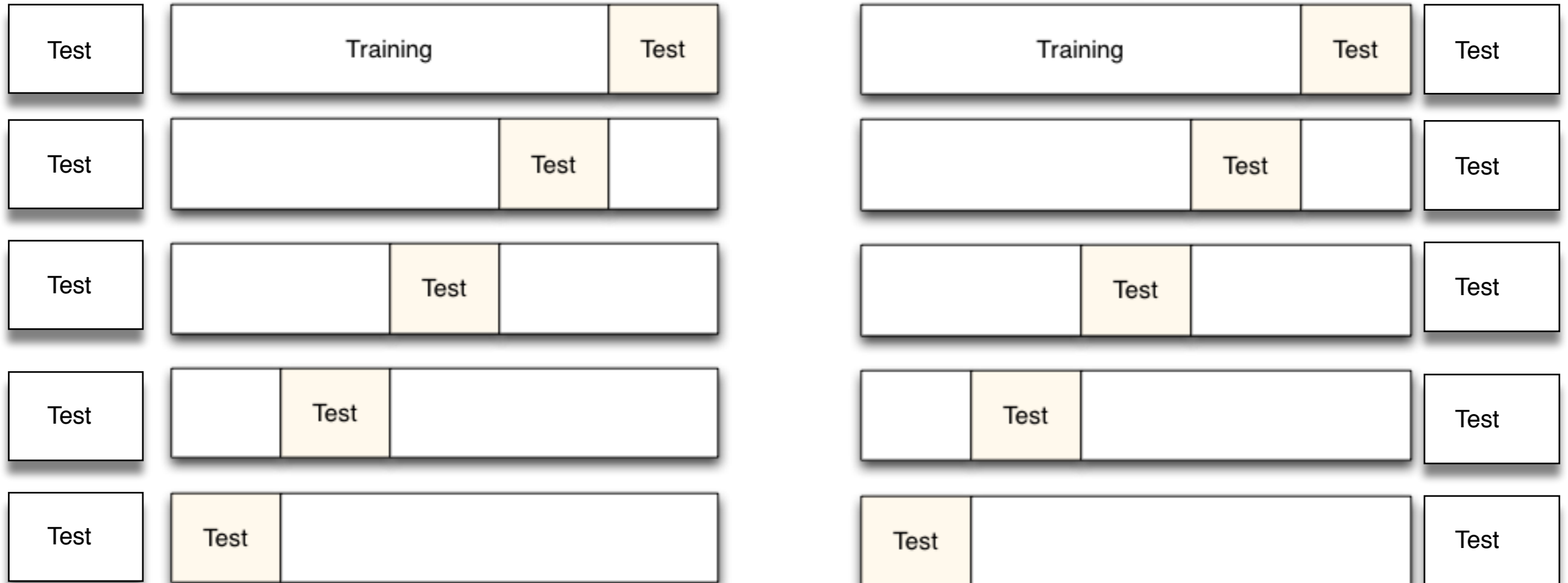
V-Fold, ($V=n$ is Leave-One-Out)

Actual protocol



Training - Validation - Test

Perils of data mining



End of PART I

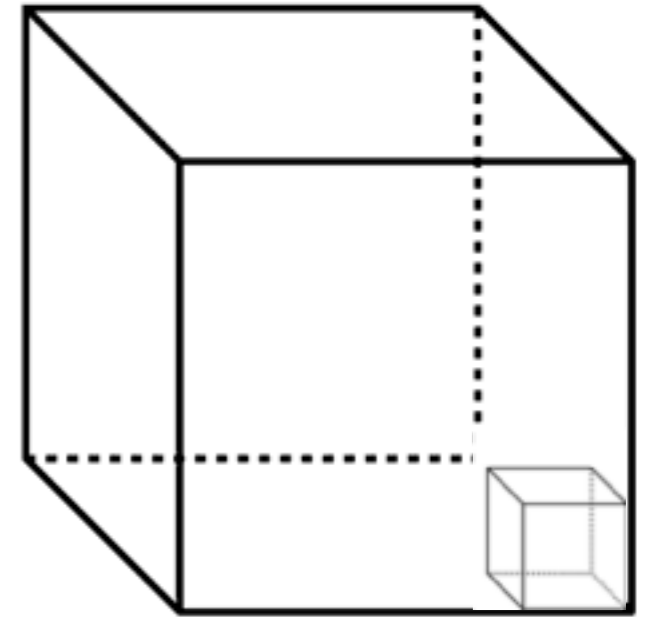
- Local methods
- Bias-Variance
- Cross Validation

Stability - Overfitting - Bias/Variance - Cross-Validation

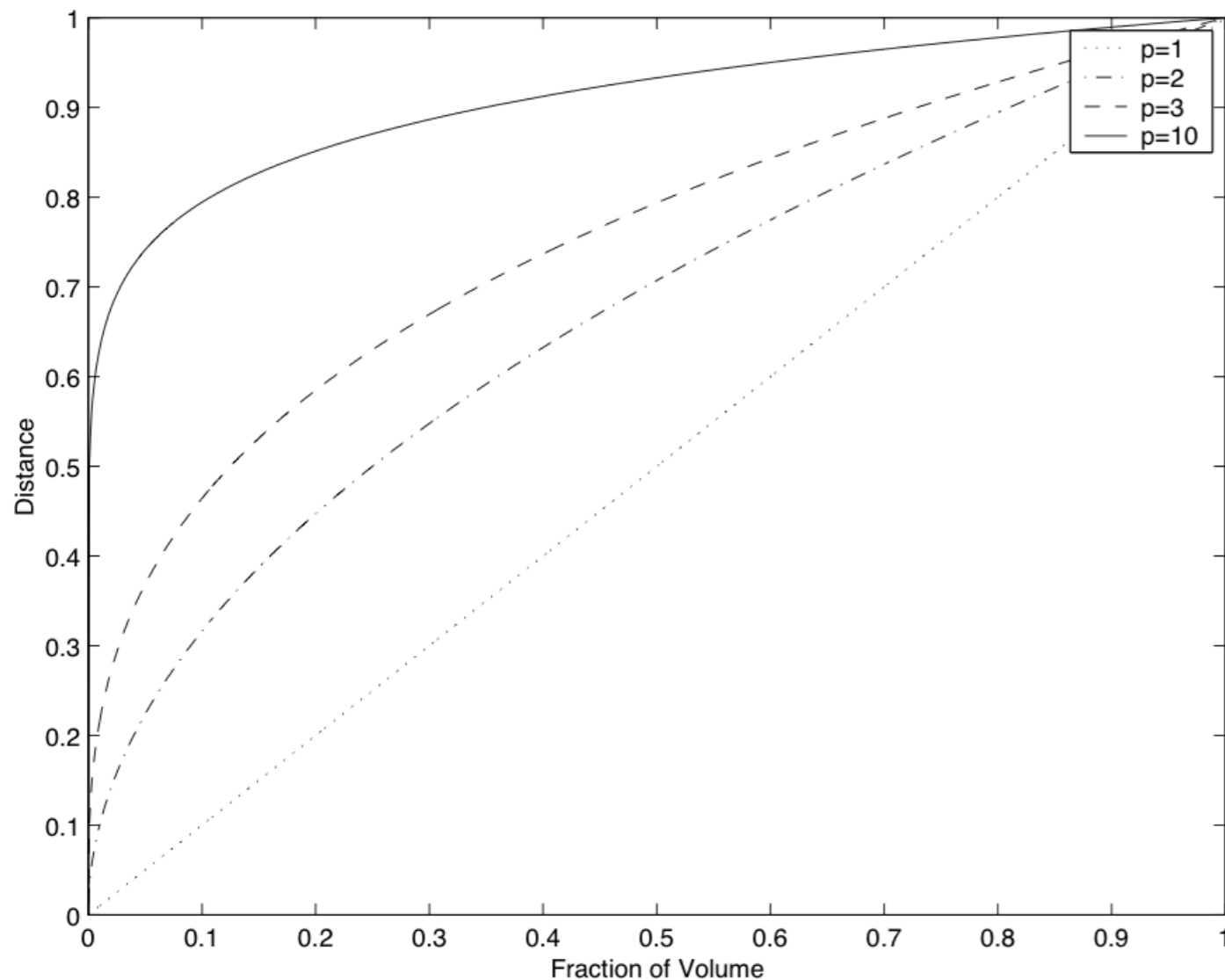
End of the Story?

High Dimensions and Neighborhood

tell me the length of the edge
of a cube containing 1% of the
volume of a cube with edge 1



Cubes and Dth-roots



Curse of dimensionality!

PART II

- Linear Least Squares
- Features and Kernels
- Deep Neural Nets

GOAL: Introduce the basic (global) regularization methods with linear and non linear models

Going Global + Impose Smoothness

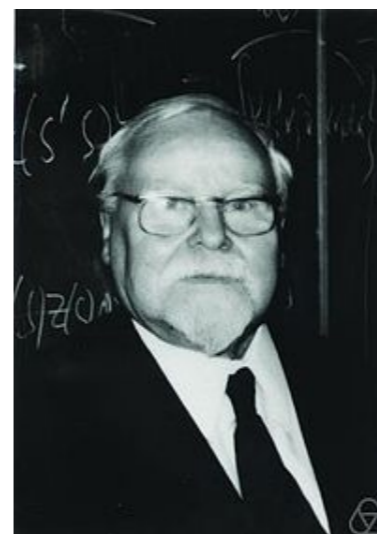
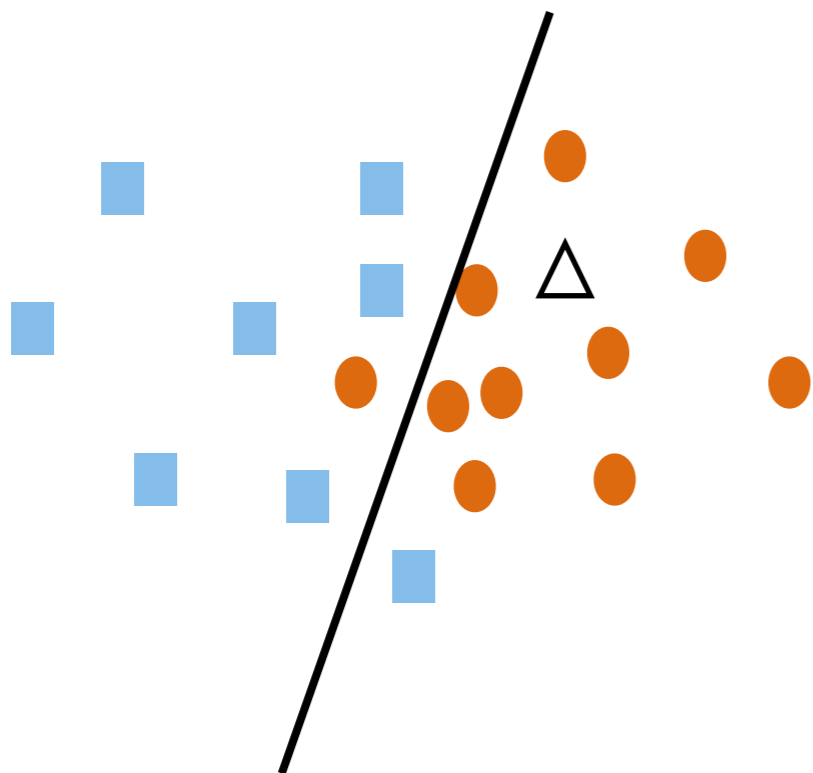
*Of all the principles which can be proposed for that purpose, I think there is none more general, more exact, and more easy of application, that of which we made use in the preceding researches, and which consists of rendering the **sum of squares of the errors** a minimum.*

(Legendre 1805)

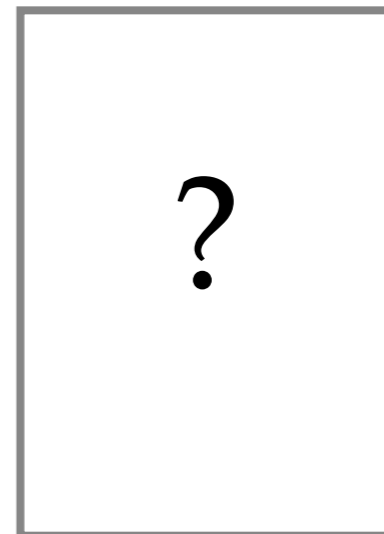


$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda w^T w, \quad \lambda \geq 0$$

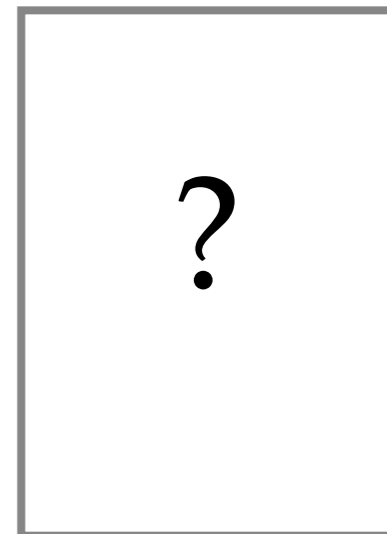
$$f(x) = w^T x = 0$$



Tikhonov '62



Phillips '62



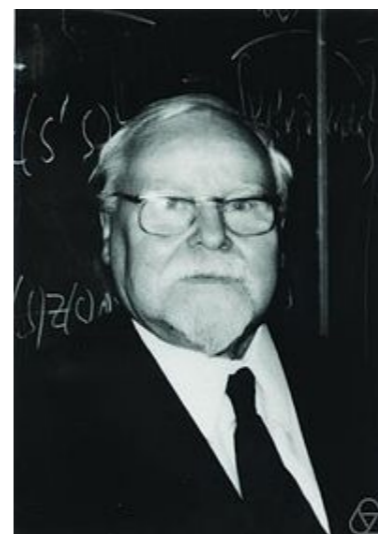
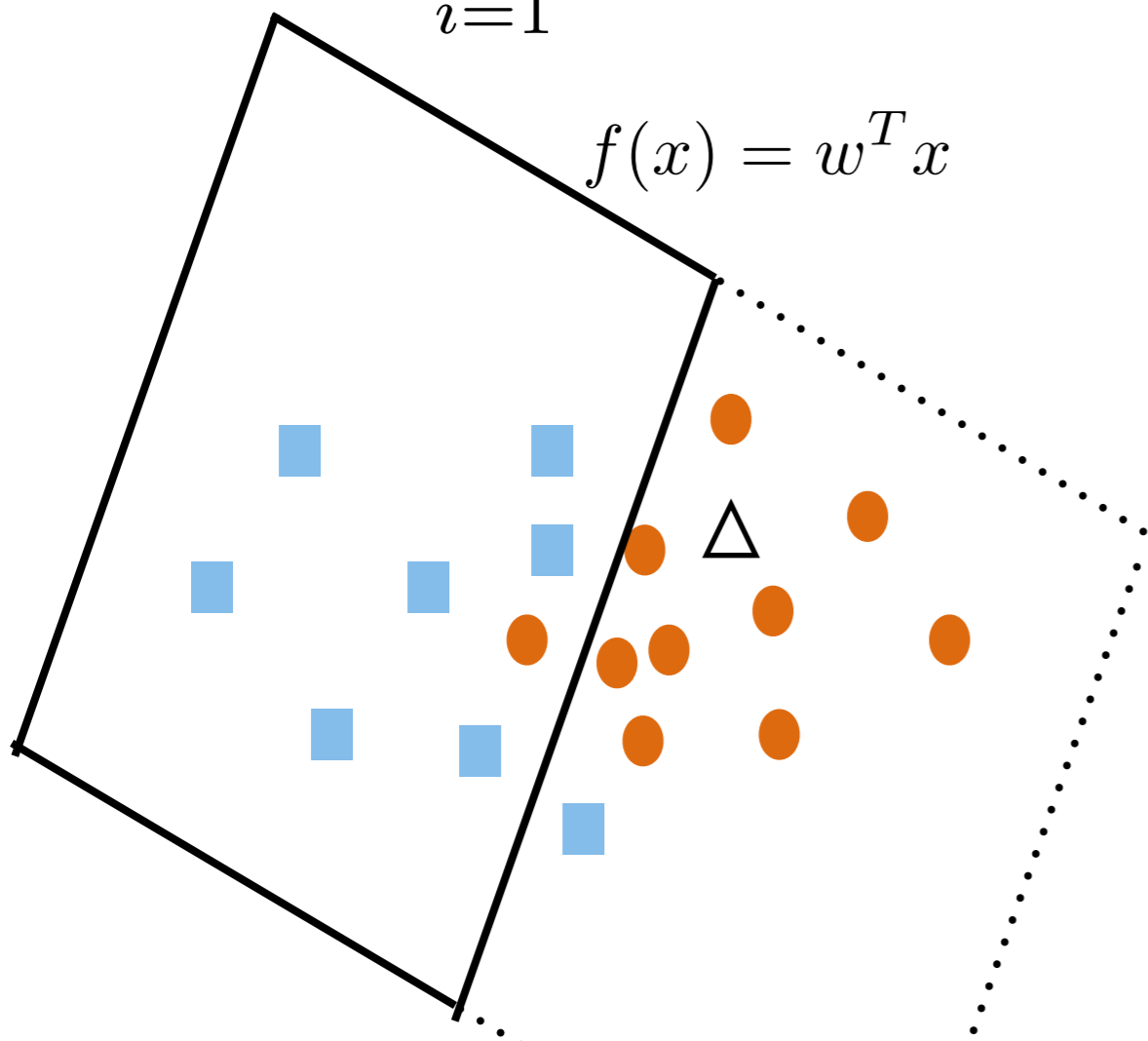
Hoerl et al. '62

*Of all the principles which can be proposed for that purpose, I think there is none more general, more exact, and more easy of application, that of which we made use in the preceding researches, and which consists of rendering the **sum of squares of the errors** a minimum.*

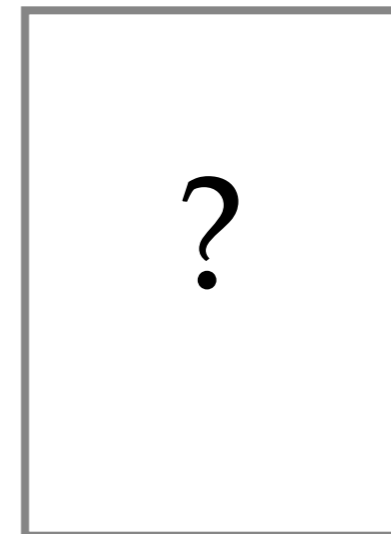
(Legendre 1805)



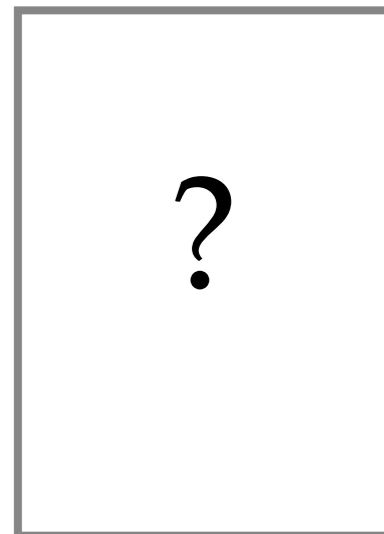
$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda w^T w, \quad \lambda \geq 0$$



Tikhonov '62



Phillips '62



Hoerl et al. '62

$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda w^T w, \quad \lambda \geq 0$$

Computations?

Statistics?

$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda w^T w, \quad \lambda \geq 0$$

Computations?

Notation $\frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 = \frac{1}{n} \|Y_n - X_n w\|^2$.

$-\frac{2}{n} X_n^T (Y_n - X_n w)$, and, $2w$ **Setting gradients...**

...to zero

$$(X_n^T X_n + \lambda n I) w = X_n^T Y_n$$

OK, but what is this doing?

Interlude: Linear Systems

$$Ma = b,$$

- If M is a diagonal $M = \text{diag}(\sigma_1, \dots, \sigma_D)$ where $\sigma_i \in (0, \infty)$ for all $i = 1, \dots, D$, then

$$M^{-1} = \text{diag}(1/\sigma_1, \dots, 1/\sigma_D), \quad (M + \lambda I)^{-1} = \text{diag}(1/(\sigma_1 + \lambda), \dots, 1/(\sigma_D + \lambda))$$

- If M is symmetric and positive definite, then considering the eigendecomposition

$$M^{-1} = V\Sigma V^T, \quad \Sigma = \text{diag}(\sigma_1, \dots, \sigma_D), \quad VV^T = I,$$

then

$$M^{-1} = V\Sigma^{-1}V^T, \quad \Sigma^{-1} = \text{diag}(1/\sigma_1, \dots, 1/\sigma_D),$$

and

$$(M + \lambda I)^{-1} = V\Sigma_\lambda V^T, \quad \Sigma_\lambda = \text{diag}(1/(\sigma_1 + \lambda), \dots, 1/(\sigma_D + \lambda))$$

$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda w^T w, \quad \lambda \geq 0$$

Statistics?

$$(X_n^T X_n + \lambda n I) w = X_n^T Y_n$$

another story that shall be told another time

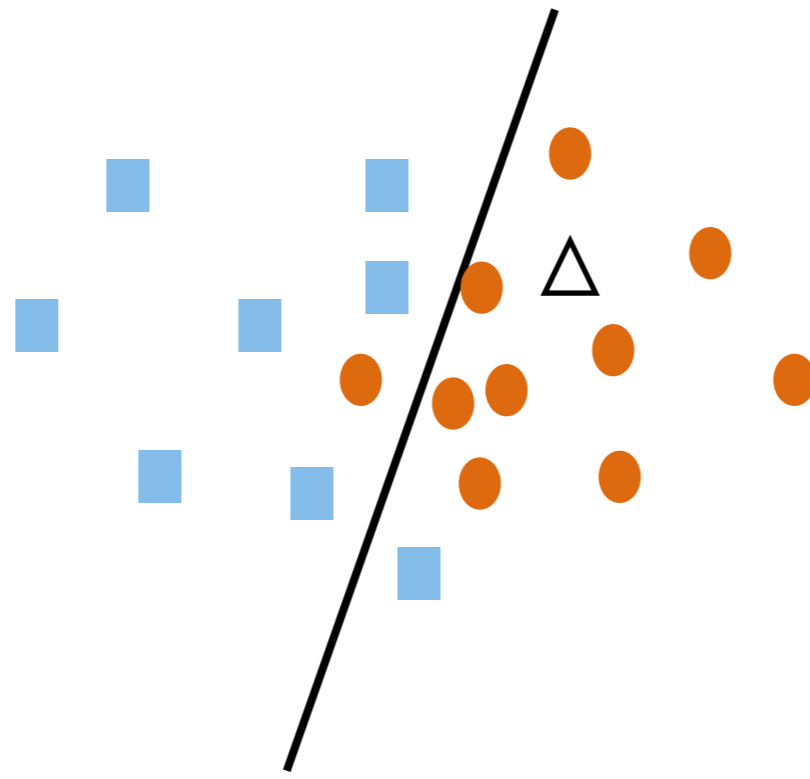
(Stein '56, Tikhonov '61)

$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda w^T w, \quad \lambda \geq 0$$

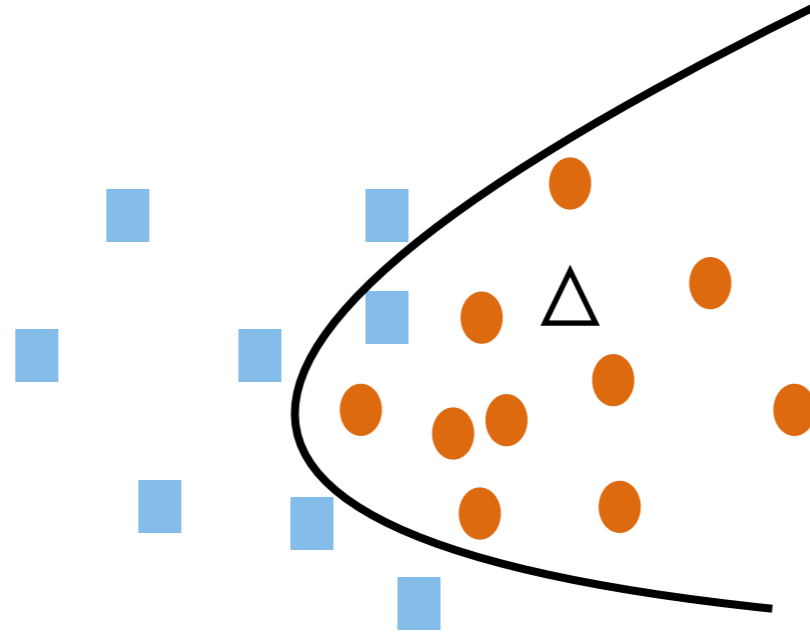
$$f_w(x) = w^T x = \sum_{i=1}^v w^i x^i \qquad \sum_{j=1}^D (w^j)^2$$

Shrinkage - Regularization

Demo



Why a linear decision rule?



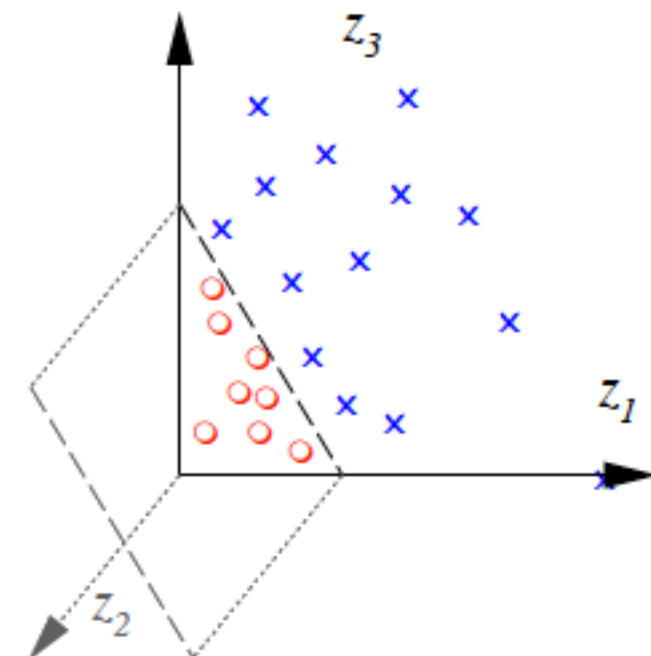
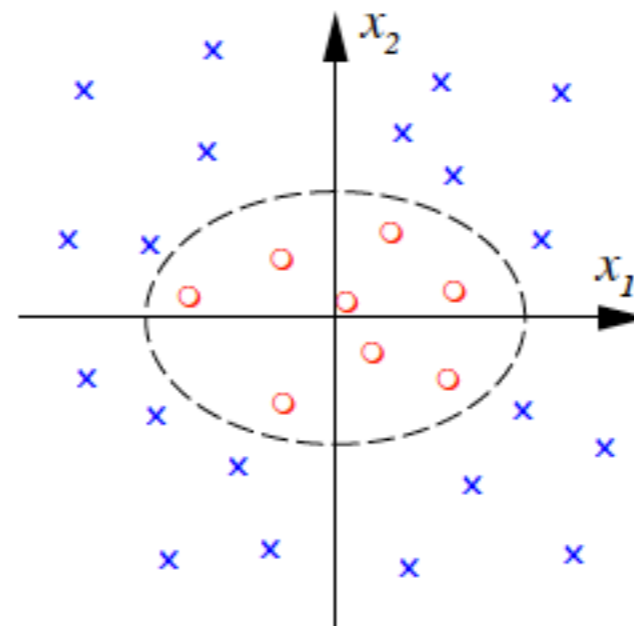
Dictionaries

$$x \mapsto \tilde{x} = (\phi_1(x), \dots, \phi_p(x)) \in \mathbb{R}^p$$

$$f(x) = w^T \tilde{x} = \sum_{j=1}^p \phi_j(x) w^j$$

$$\Phi : \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

$$(x_1, x_2) \mapsto (z_1, z_2, z_3) := (x_1^2, \sqrt{2}x_1x_2, x_2^2)$$



$$(X_n^T X_n + \lambda n I)w = X_n^T Y_n \quad \mapsto \quad (\tilde{X}_n^T \tilde{X}_n + \lambda n Y)w = \tilde{X}_n^T Y_n$$

What About Computational Complexity?

Complexity Vademecum

M n by p matrix and v, v' p dimensional vectors

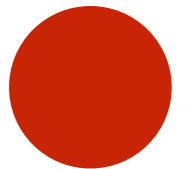
- $v^T v' \mapsto O(p)$
- $Mv' \mapsto O(np)$
- $MM^T \mapsto O(np^2)$
- $(MM^T)^{-1} \mapsto O(n^3)$

$$(X_n^T X_n + \lambda n I) w = X_n^T Y_n \quad \mapsto \quad (\tilde{X}_n^T \tilde{X}_n + \lambda n Y) w = \tilde{X}_n^T Y_n$$

What About Computational Complexity?

$$O(p^3) + O(p^2 n)$$

What if p is much larger than n ?



$$(X_n^T X_n + \lambda n I)^{-1} X_n^T = X_n^T (X_n X_n^T + \lambda n I)^{-1}$$

$$w = X_n^T \underbrace{(X_n X_n^T + \lambda n I)^{-1} Y_n}_c = \sum_{i=1}^n x_i^T c_i$$

$$(X_n^T X_n + \lambda n I)^{-1} X_n^T = X_n^T (X_n X_n^T + \lambda n I)^{-1}$$

$$w = X_n^T \underbrace{(X_n X_n^T + \lambda n I)^{-1} Y_n}_c = \sum_{i=1}^n x_i^T c_i$$

Computational Complexity: ~~$O(p^3) + O(p^2 n)$~~ $O(n^3) + O(p n^2)$

$$(X_n^T X_n + \lambda n I)^{-1} X_n^T = X_n^T (X_n X_n^T + \lambda n I)^{-1}$$

$$w = X_n^T \underbrace{(X_n X_n^T + \lambda n I)^{-1} Y_n}_c = \sum_{i=1}^n x_i^T c_i$$

Kernels $w = \sum_{j=1}^n x_j c_j \Rightarrow f(x) = x^T w = \sum_{j=1}^n \underbrace{x^T x_j}_{K(x, x_j)} c_j$

$$(K_n + \lambda n I)c = Y_n, \quad (K_n)_{i,j} = K(x_i, x_j)$$

- the linear kernel $K(x, x') = x^T x'$,
- the polynomial kernel $K(x, x') = (x^T x' + 1)^d$,
- the Gaussian kernel $K(x, x') = e^{-\frac{\|x - x'\|^2}{2\sigma^2}}$,

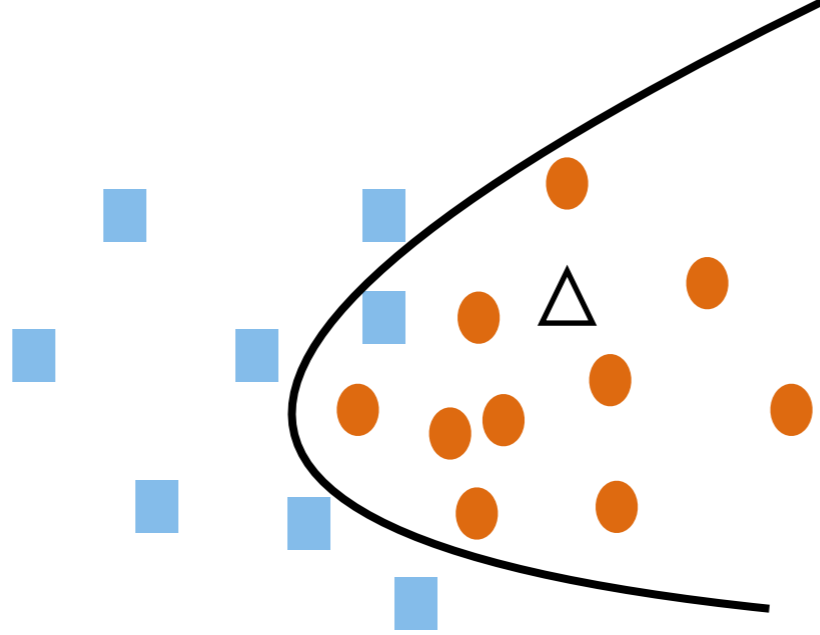
$$\hat{f}(x) = \sum_{i=1}^n K(x_i, x)c_i.$$

things I won't tell you about

- Reproducing Kernel Hilbert Spaces
- Gaussian Processes
- Integral Equations
- Sampling Theory / Inverse Problems

- Loss functions- SVM, Logistic...
- Multi - task, labels, outputs, classes

Demo



$$f(x) = w^T \tilde{x} = \sum_{j=1}^p \phi_j(x) w^j$$

$$\hat{f}(x) = \sum_{i=1}^n K(x_i, x) c_i.$$

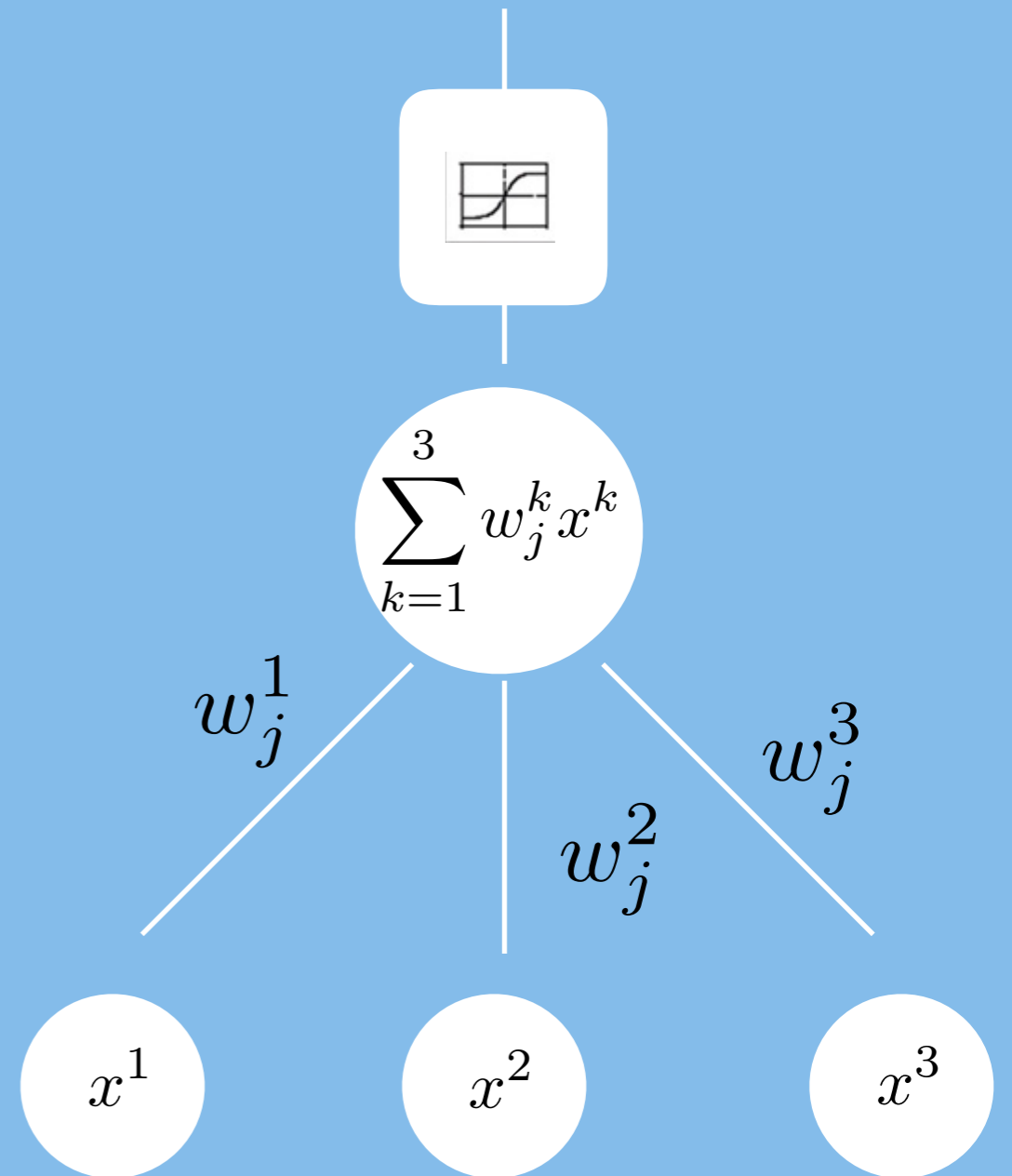
Neural Networks

$$f(x) = \sum_{j=1}^p \beta_j \sigma(w_j^T x + b_j)$$

Neural Networks

$$f(x) = \sum_{j=1}^p \beta_j \sigma(w_j^T x + b_j)$$

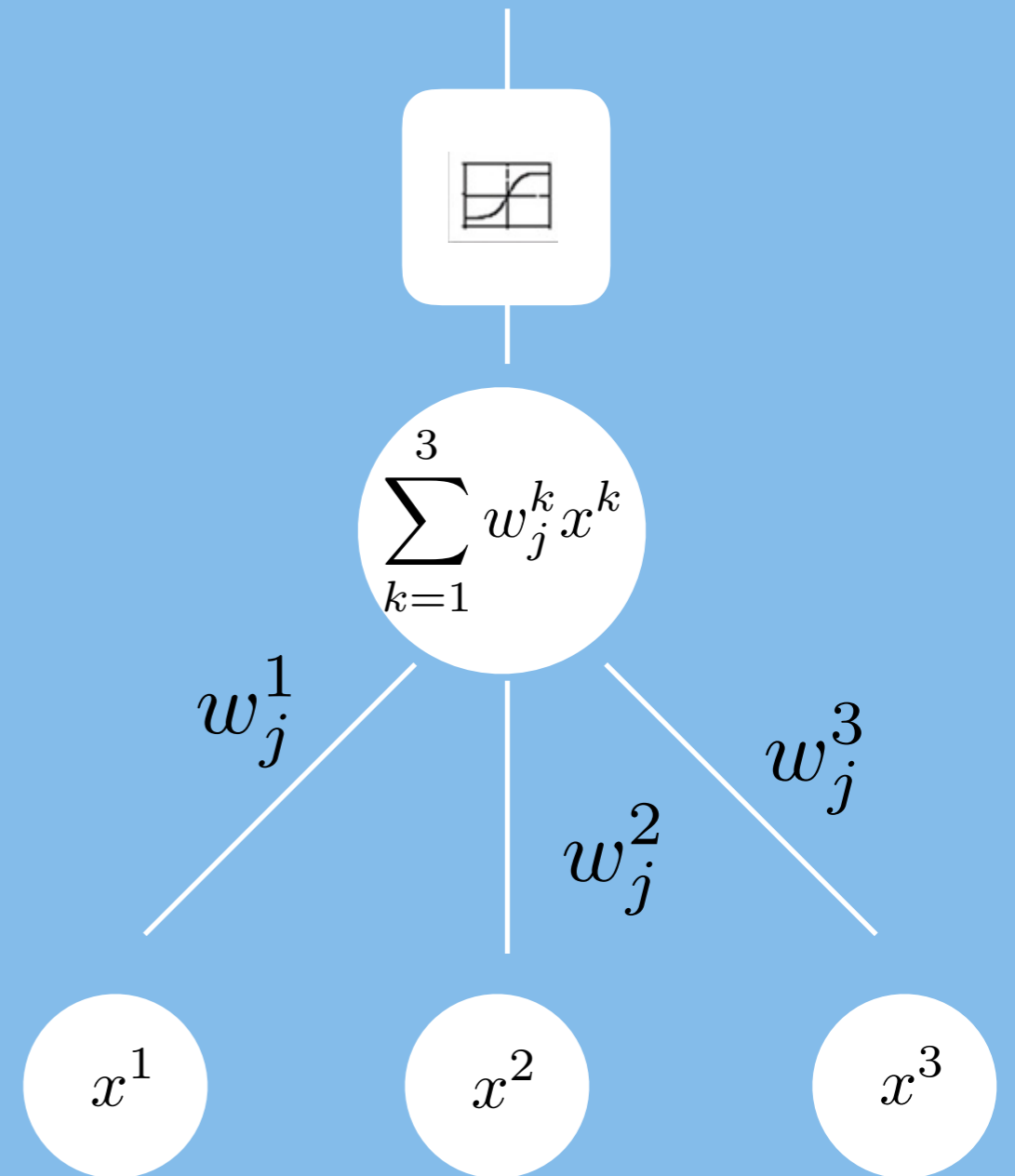
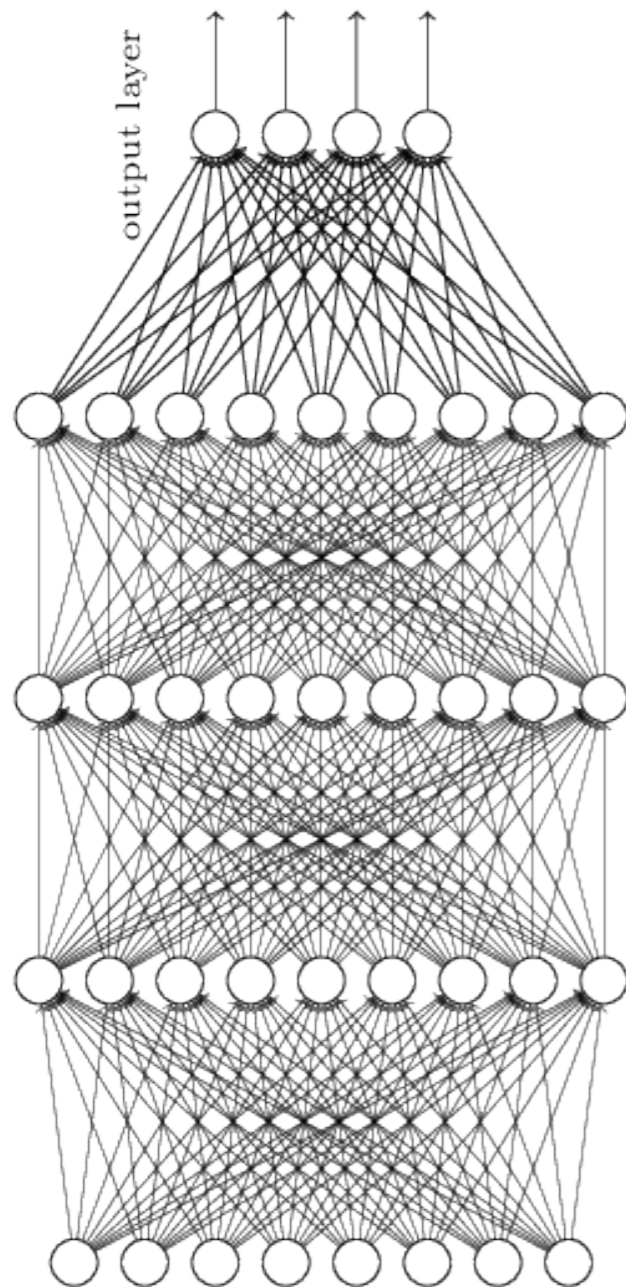
$$\sigma(w_j^T x + b_j) = \sigma\left(\sum_{k=1}^d w_j^k x^k + b_j\right)$$



HI, I AM A NEURON

Deep Neural Networks

$$f_W(x) = \beta^T \sigma(W_L \sigma(W_{L-1} \dots \sigma(W_1 x)))$$



HI, I AM A NEURON

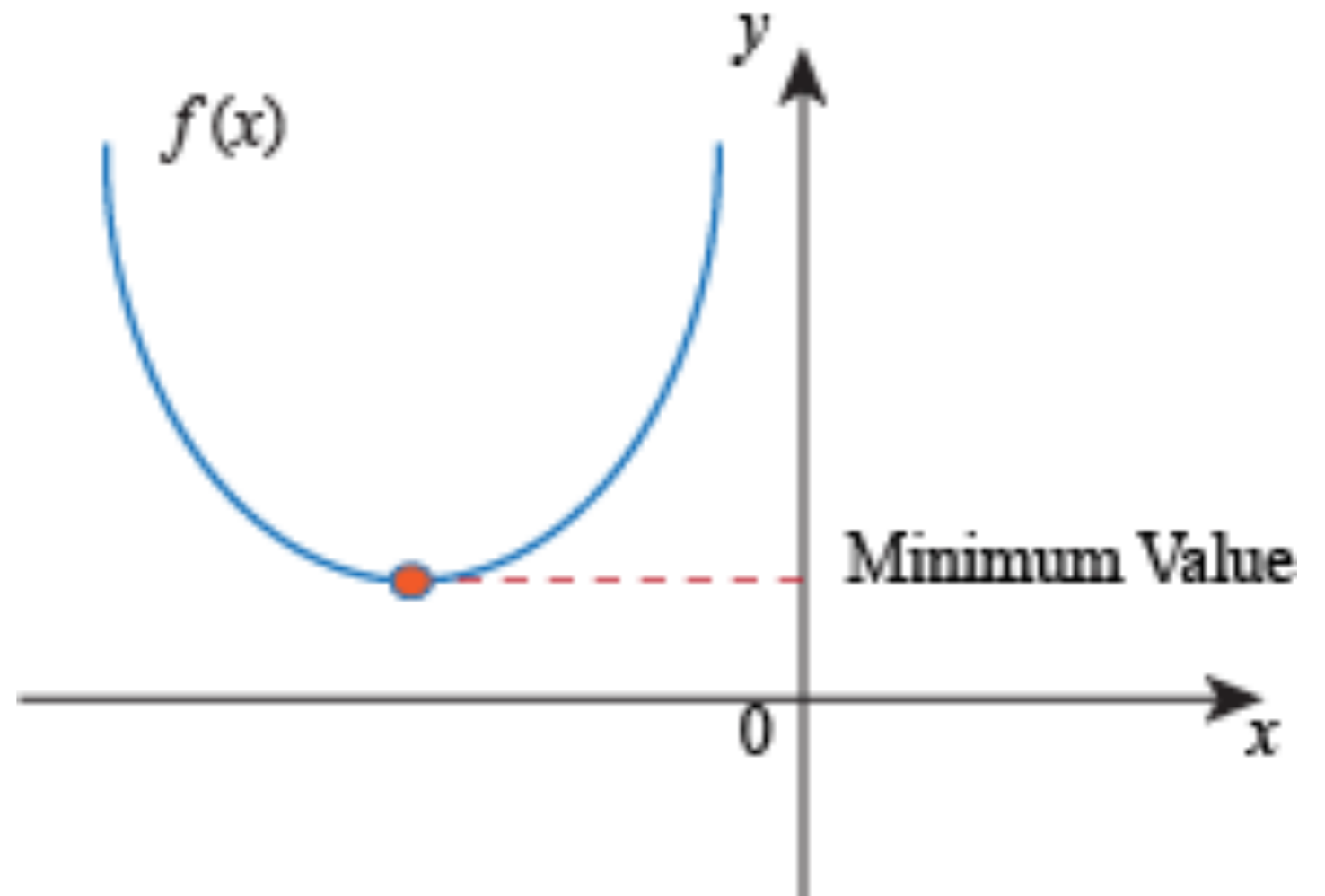
Newton method/Gradient descent

$$\min_W \sum_{i=1}^n (f_W(x_i) - y_i)^2$$

$$W_{t+1} = W_t - \gamma \nabla_W \sum_{i=1}^n (f_{W_t}(x_i) - y_i)^2$$

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

$n = 1, 2, 3, \dots$

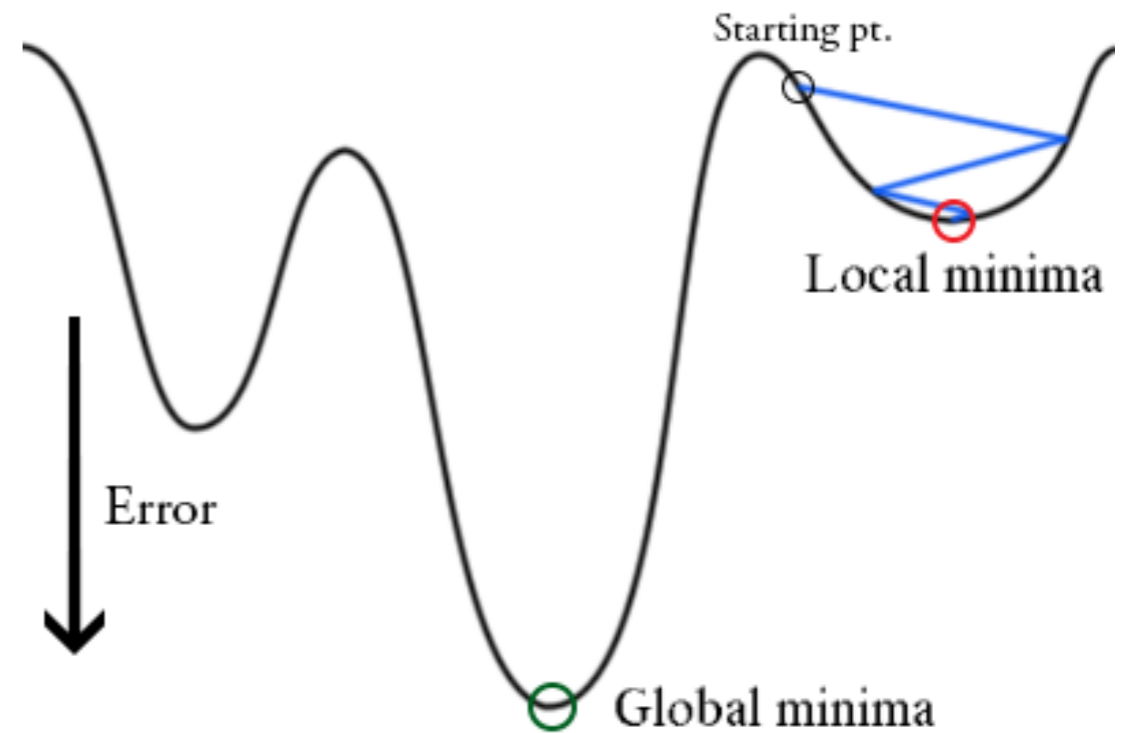
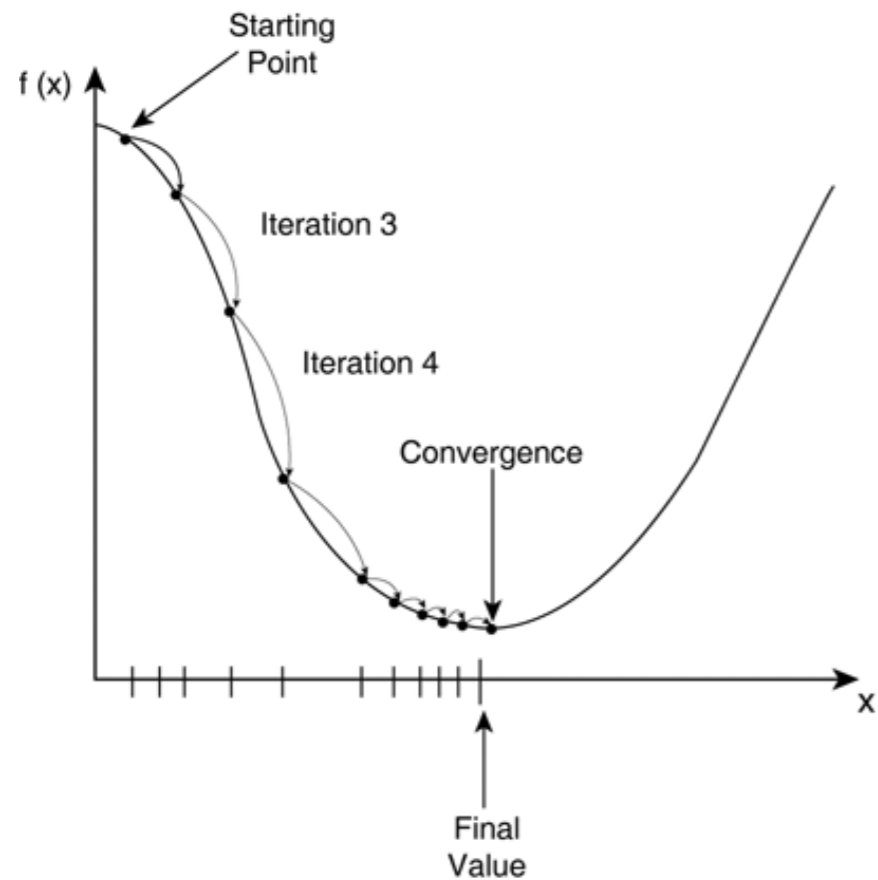


Stochastic gradient

$$W_{t+1} = W_t - \gamma \nabla_W \sum_{i=1}^n (f_{W_t}(x_i) - y_i)^2$$



$$W_{t+1} = W_t - \gamma \nabla_W (f_{W_t}(x_t) - y_t)^2$$



linear regression/logistic/svm

neural nets

Demo

End of PART II

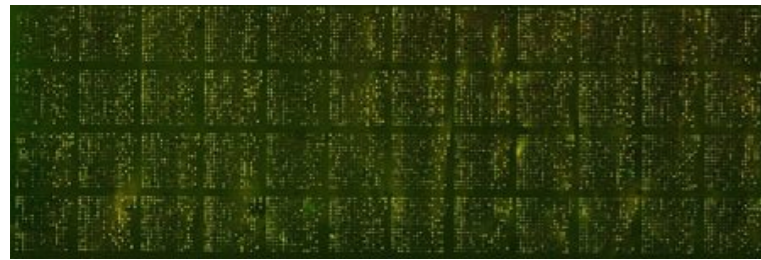
- Linear Least Squares
- Kernel and features
- Deep Neural Nets

PART III

- a) Variable Selection: OMP
- b) Dimensionality Reduction: PCA

GOAL: To introduce methods that allow to learn *interpretable* models from data

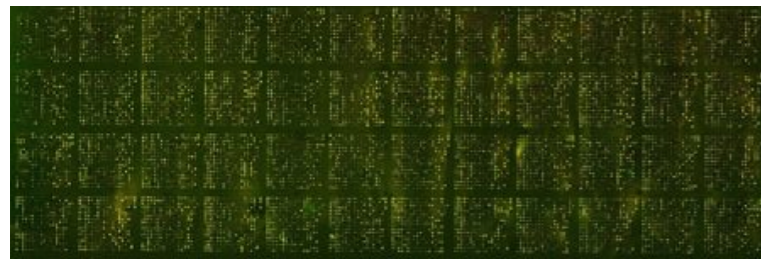
n patients p gene expression measurements



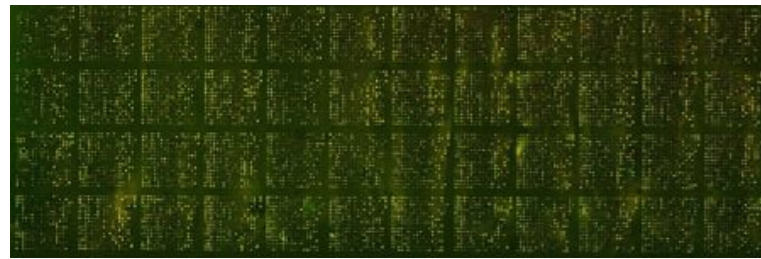
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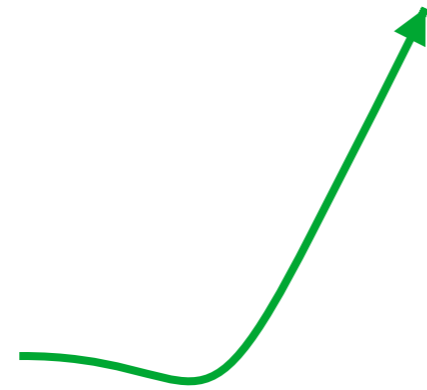
;



...



$$X_n = \begin{pmatrix} x_1^1 & \dots & \dots & \dots & x_1^p \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_n^1 & \dots & \dots & \dots & x_n^p \end{pmatrix}; Y_n = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$



$$f_w(x) = w^T x = \sum_{j=1}^D x^j w^j$$

Which variables are important for prediction?

or

Torture the data until they confess

Sparsity: only some of the coefficients are non zero

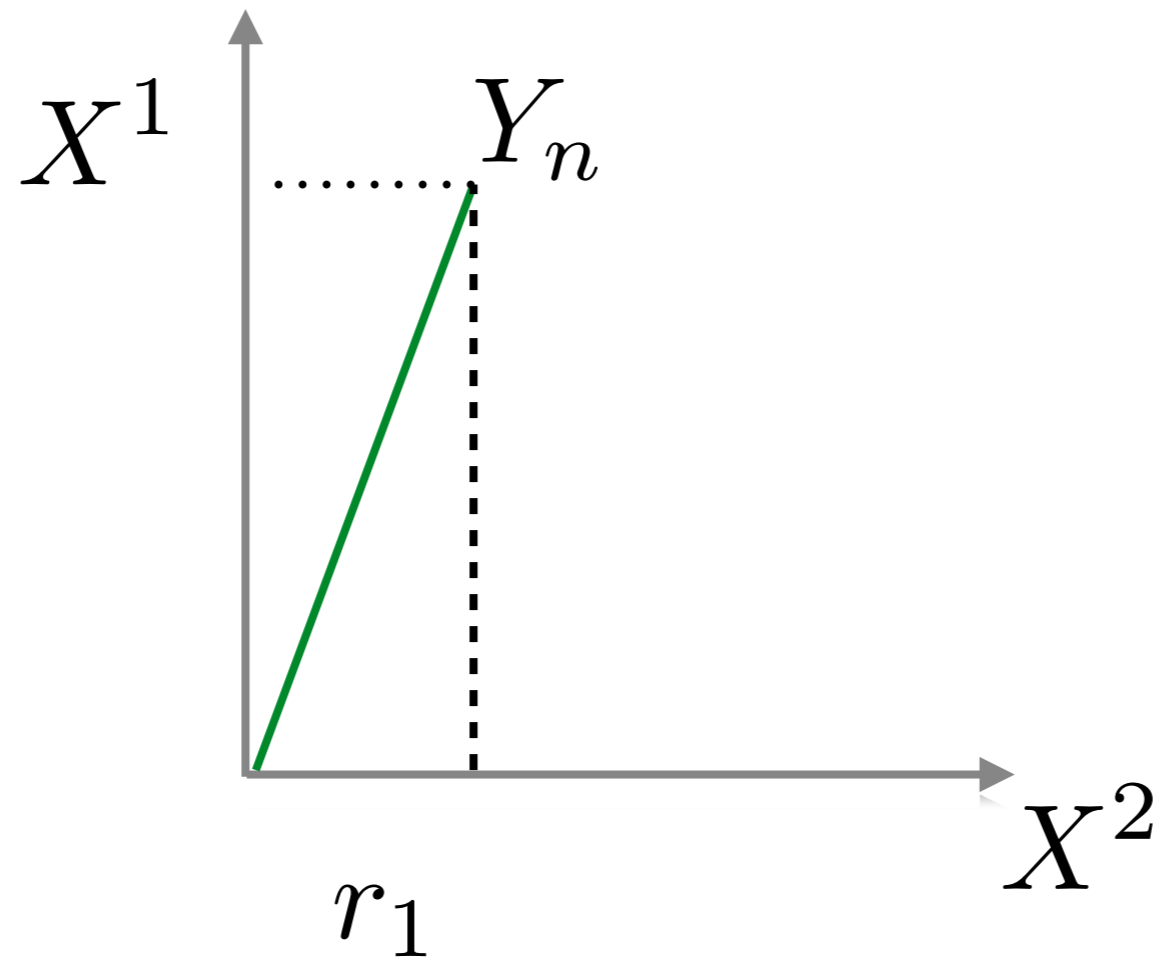
Brute Force Approach

check all individual variables, then all couple, triplets....

$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - f_w(x_i))^2 + \lambda \|w\|_0,$$

$$\|w\|_0 = |\{j \mid w^j \neq 0\}|$$

Greedy approaches/Matching Pursuit



- (1) initialize the residual, the coefficient vector, and the index set,
- (2) find the variable most correlated with the residual,
- (3) update the index set to include the index of such variable,
- (4) update/compute coefficient vector,
- (5) update residual.

$$r_0 = Y_n, \quad w_0 = 0, \quad I_0 = \emptyset.$$

Matching Pursuit

(Mallat Zhang '93)

for $i = 1, \dots, T - 1$

$$k = \arg \max_{j=1, \dots, D} a_j, \quad a_j = \frac{(r_{i-1}^T X^j)^2}{\|X^j\|^2}, \quad \textcircled{*}$$

$$I_i = I_{i-1} \cup \{k\}$$

$$w_i = w_{i-1} + w_k, \quad w_k k = v_k e_k$$


$$r_i = r_{i-1} - X w^k.$$

end

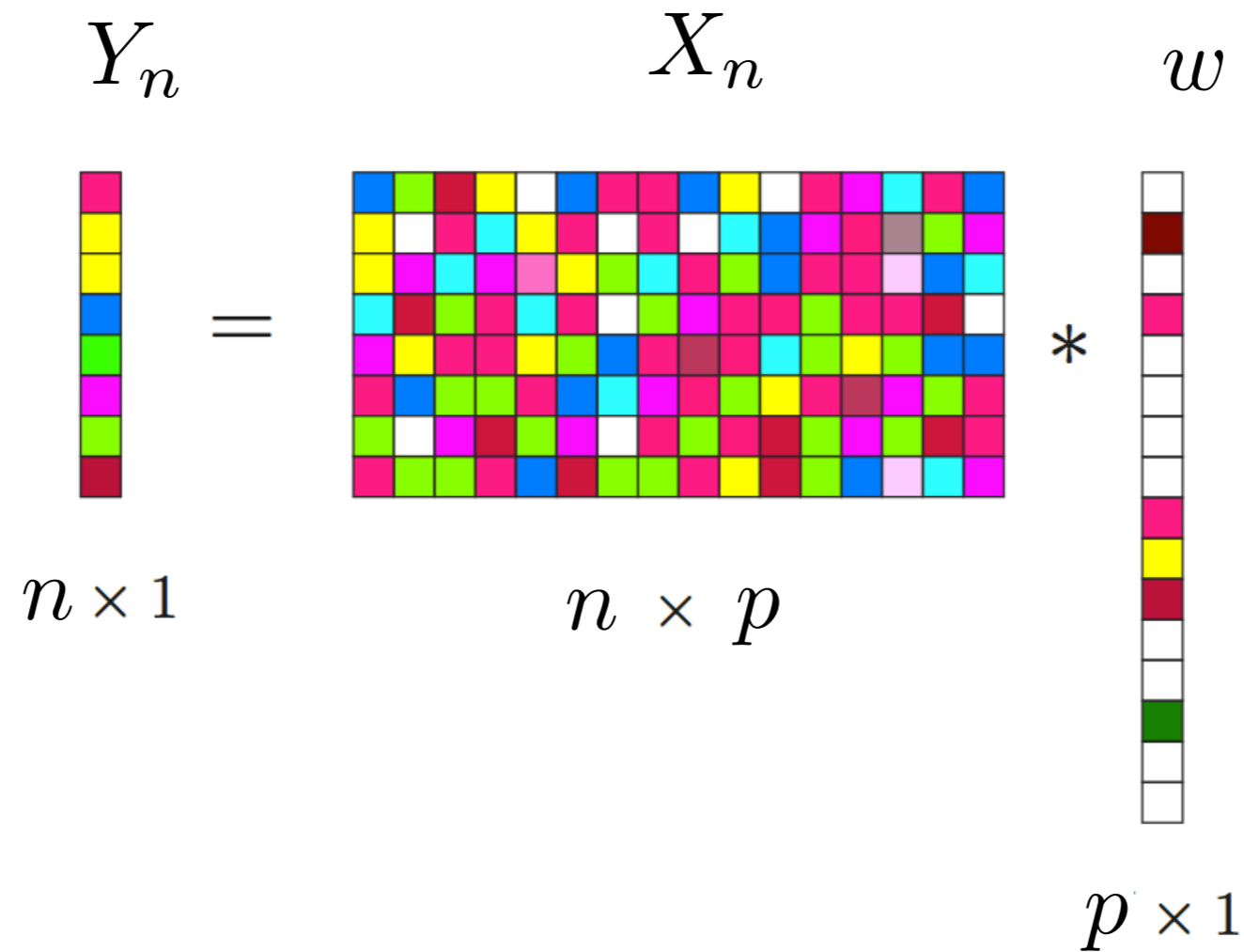
$$\textcircled{*} \quad v^j = \frac{r_{i-1}^T X^j}{\|X^j\|^2} = \arg \min_{v \in \mathbb{R}} \|r_{i-1} - X^j v\|^2, \quad \|r_{i-1} - X^j v^j\|^2 = \|r_{i-1}\|^2 - a_j$$

Basis Pursuit/Lasso

(Chen Donoho Saunders ~95, Tibshirani '96)

$$\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - f_w(x_i))^2 + \lambda \|w\|_1,$$
$$\|w\|_1 = \sum_{j=1}^D |w^j|$$


Problem is now **convex** and can be solved using convex optimization, in particular so called *proximal methods*



things I won't tell you about

- Solving underdetermined systems
- Sampling theory
- Compressed Sensing
- Structured Sparsity
- From vector to matrices- from sparsity to low rank

End of PART III a)

- **a) Variable Selection: OMP**
- **b) Dimensionality Reduction: PCA**

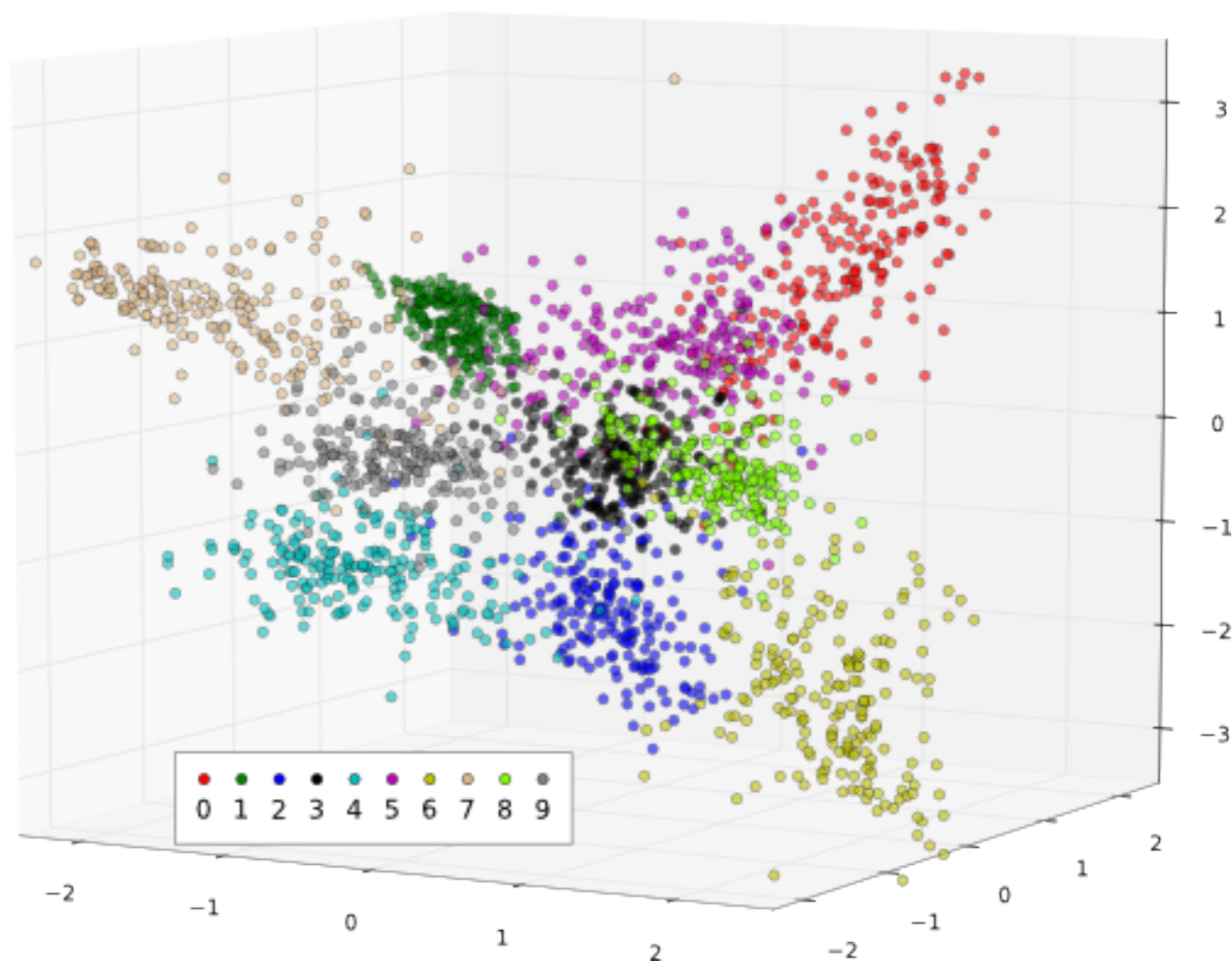
Interpretability - Sparsity - Greedy & Convex Relaxation Approaches

PART III b)

- a) Variable Selection: OMP
- **b) Dimensionality Reduction: PCA**

GOAL: To introduce methods that allow to reduce data dimensionality in absence of labels, namely **unsupervised learning**

Dimensionality Reduction for Data Visualization



Dimensionality Reduction

$$M : X = \mathbb{R}^D \rightarrow \mathbb{R}^k, \quad k \ll D,$$

Dimensionality Reduction

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Consider first $k = 1$

Dimensionality Reduction

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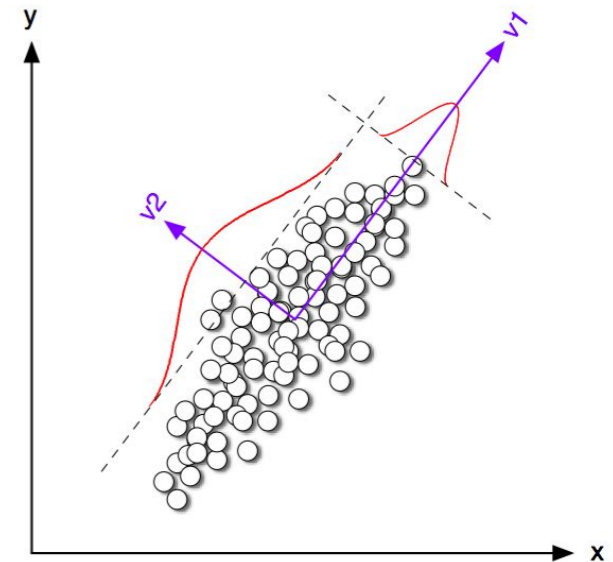
PCA

$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^n \|x_i - (w^T x_i)w\|^2,$$

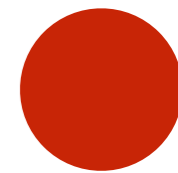
$w^T w = 1$

Computations?

Statistics?

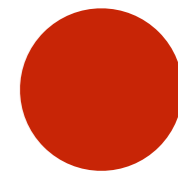


$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^n \|x_i - (w^T x_i)w\|^2,$$



Statistics?

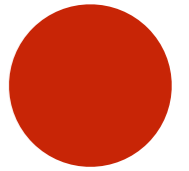
$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^n \|x_i - (w^T x_i)w\|^2,$$



Statistics?

$$\|x_i - (w^T x_i)w\|^2 = \|x_i\|^2 - (w^T x_i)^2;$$

$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^n \|x_i - (w^T x_i)w\|^2,$$

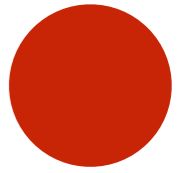


Statistics?

$$\|x_i - (w^T x_i)w\|^2 = \|x_i\|^2 - (w^T x_i)^2,$$

$$\implies \max_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^n (w^T x_i)^2.$$

$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^n \|x_i - (w^T x_i)w\|^2,$$

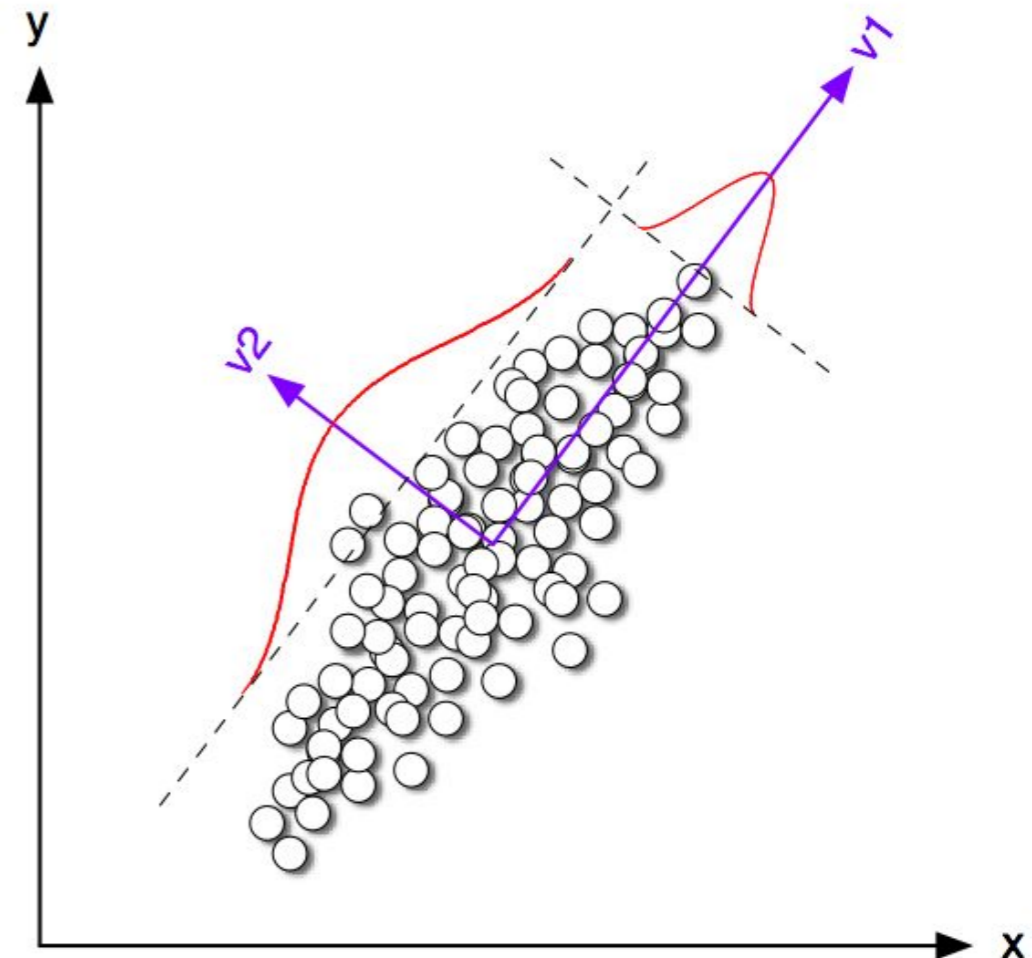


Statistics?

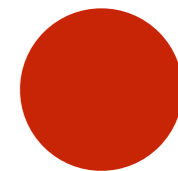
$$\|x_i - (w^T x_i)w\|^2 = \|x_i\|^2 - (w^T x_i)^2,$$

$$\implies \max_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^n (w^T x_i)^2.$$

$$\implies \max_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^n (w^T (x_i - \bar{x}))^2,$$

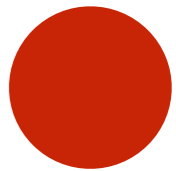


$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^n \|x_i - (w^T x_i)w\|^2,$$



Computations?

$$\min_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^n \|x_i - (w^T x_i)w\|^2,$$



Computations?

$$\max_{w \in \mathbb{S}^{D-1}} \frac{1}{n} \sum_{i=1}^n (w^T x_i)^2 \Leftrightarrow \max_{w \in \mathbb{S}^{D-1}} w^T C_n w, \quad C_n = \frac{1}{n} \sum_{i=1}^n x_i x_i^T$$

w_1 max eigenvector of C_n

$$\frac{1}{n} \sum_{i=1}^n (w^T x_i)^2 = \frac{1}{n} \sum_{i=1}^n w^T x_i w^T x_i = \frac{1}{n} \sum_{i=1}^n w^T x_i x_i^T w = w^T \left(\frac{1}{n} \sum_{i=1}^n x_i x_i^T \right) w$$


Dimensionality Reduction

$$M : X = \mathbb{R}^D \rightarrow \mathbb{R}^k, \quad k \ll D,$$

What about $k = 2$?

...

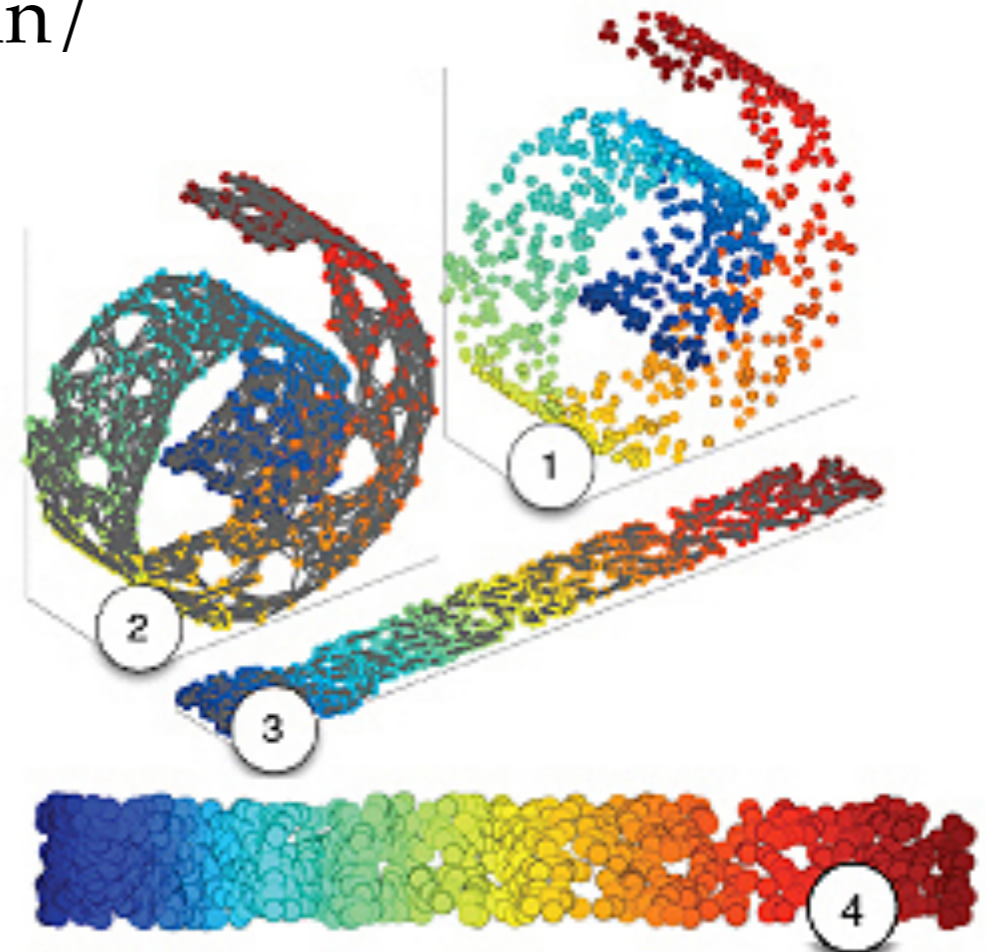
w_2 second eigenvector of C_n


$$\max_{\substack{w \in \mathbb{S}^{D-1} \\ w \perp w_1}} w^T C_n w, \quad C_n = \frac{1}{n} \sum_{i=1}^n x_i x_i^T.$$

$$M : X = \mathbb{R}^D \rightarrow \mathbb{R}^k, \quad k \ll D,$$

things I won't tell you about

- **Random Maps:** Johnson-Linderstrauss Lemma
- **Non Linear Maps:** Kernel PCA, Laplacian/
Diffusion maps



End of PART III b)

- a) Variable Selection: OMP
- **b) Dimensionality Reduction: PCA**

Interpretability - Sparsity - Greedy & Convex Relaxation Approaches

The End



PART IV

- Matlab practical session

Afternoon