

Computational Models of Vision

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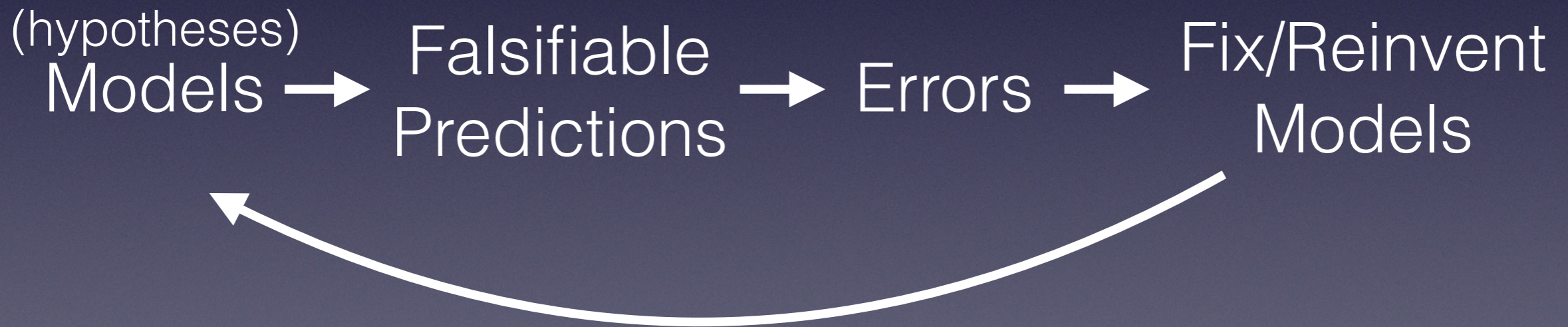
Encoding Edition

Overview - Encoding Models

- Why studying vision?
- What do we know about brain's representation of the visual world?
- What models are there for these processes?

Why Models?

- Why do we need models?
- How can we use models in science?



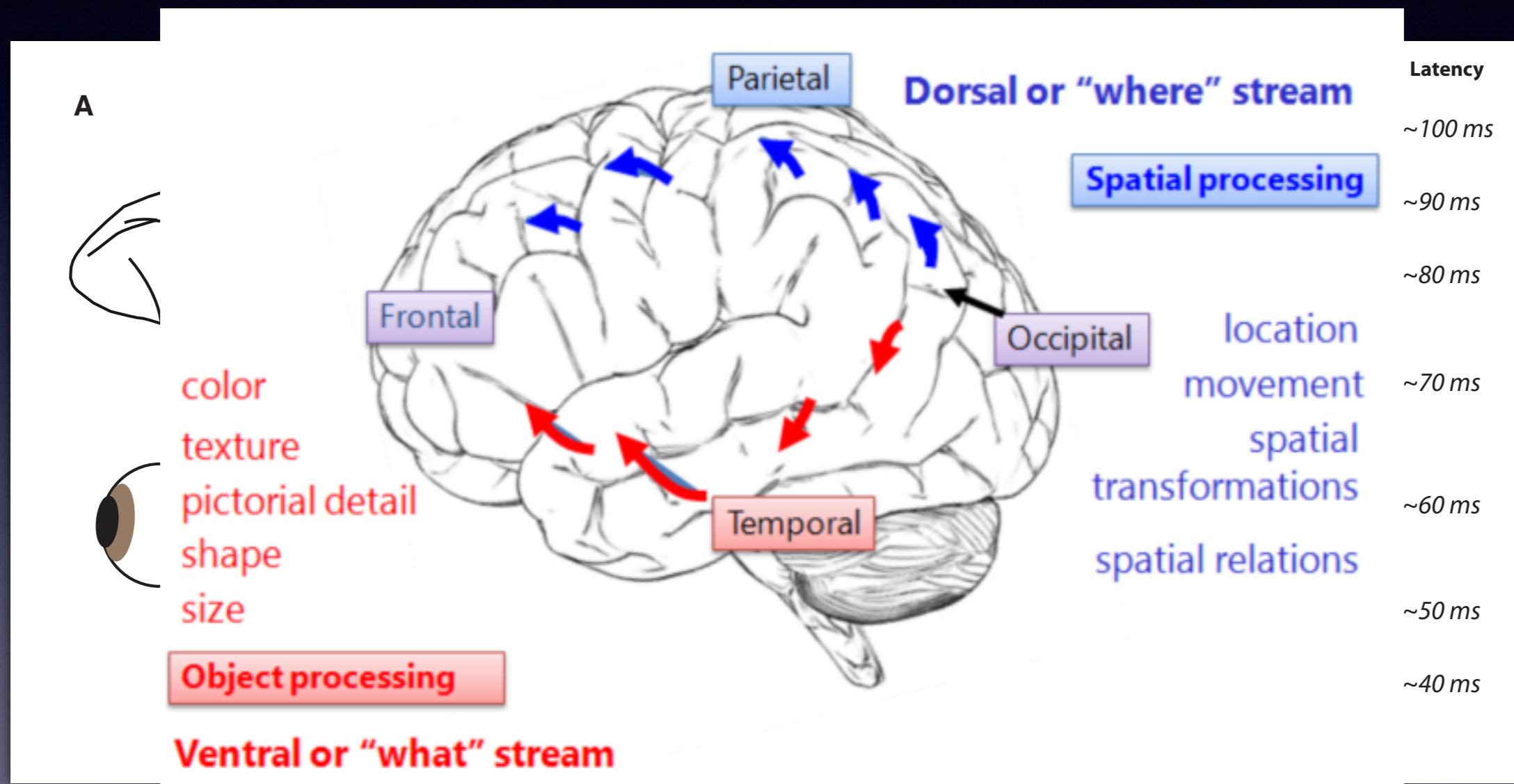
"Truth will sooner come out from error than from confusion." Francis Bacon

Why Vision?

1. A window into how neural networks build a compact representation of the world.
2. How the encoded image is represented by the neural response within the peripheral and early cortical visual pathways.
3. What's the role of these representations in efficient image coding.

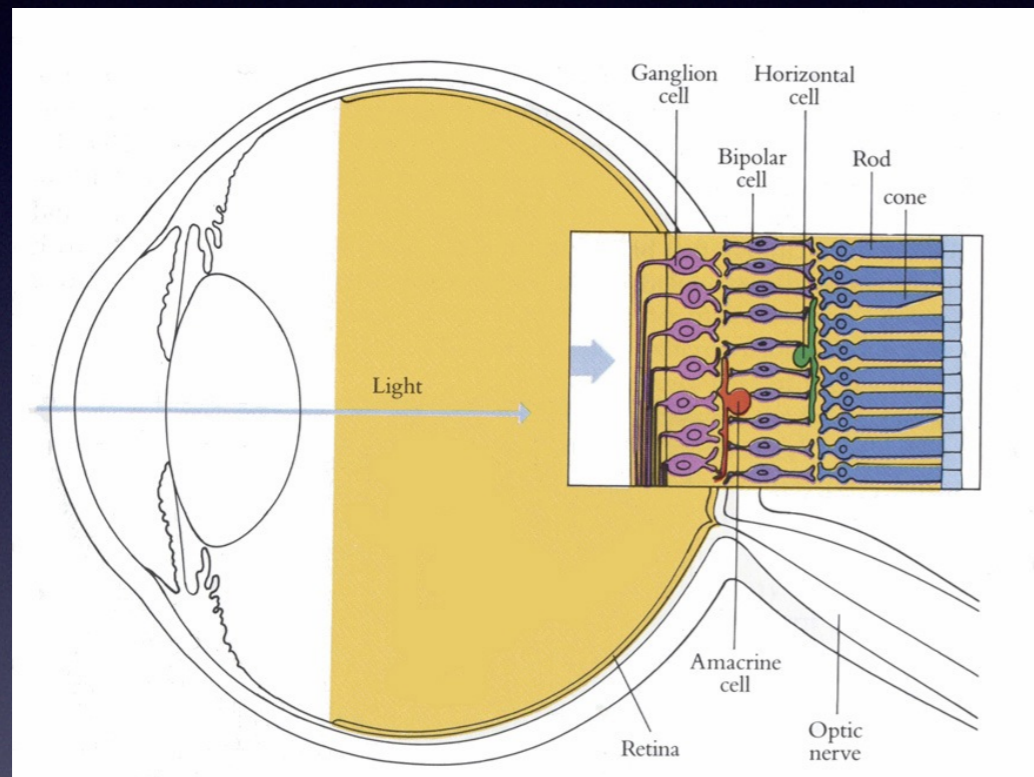
What we know about vision in primates

Visual Processing Streams

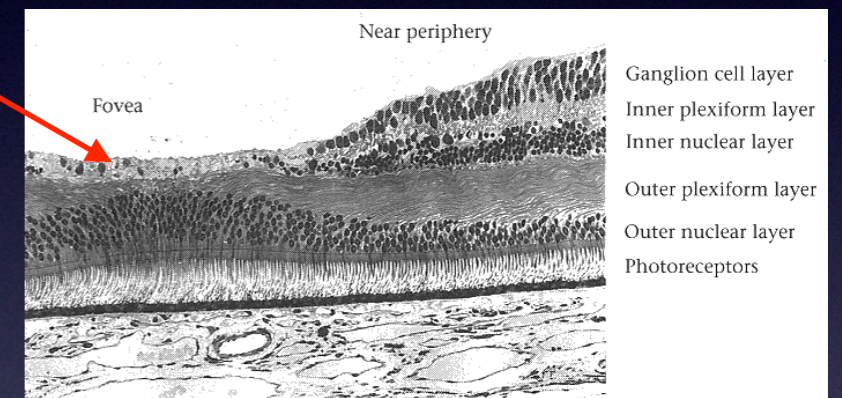


Ventral Stream

Image Formation - Retina



Only one layer
Cone photoreceptors



Rods and Cones: encode the image in different intensity ranges.

1. There is only a narrow region of high visual acuity in the fovea.
2. Dynamic range of sensors is very small.
3. Representation of wavelength is coarse.



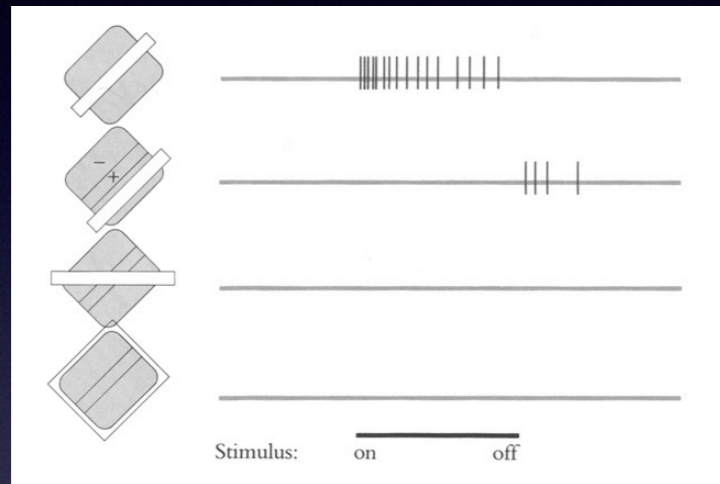
Things We Know

Lateral Geniculate Nucleus (LGN)

- Receives input from Retina through the optic nerve
- Two major streams:
 1. **Parvocellular**: high-spatial freq + low-temporal-freq
 2. **Magnocellular**: low-spatial freq + high-temporal-freq

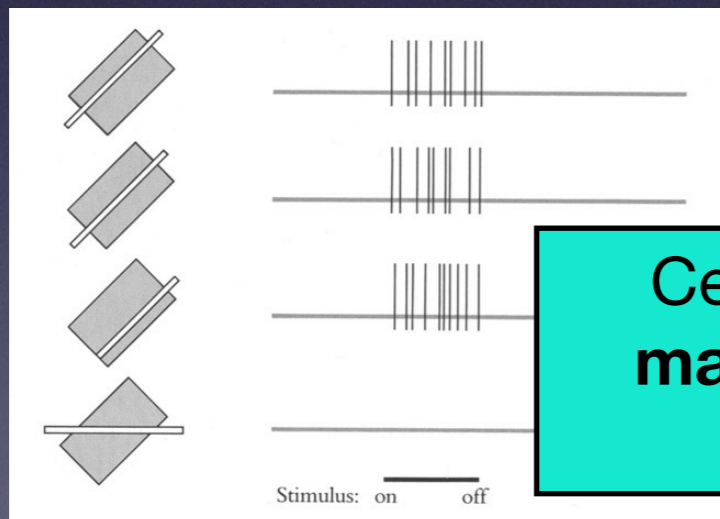
Primary Visual Cortex - V1

Simple cell



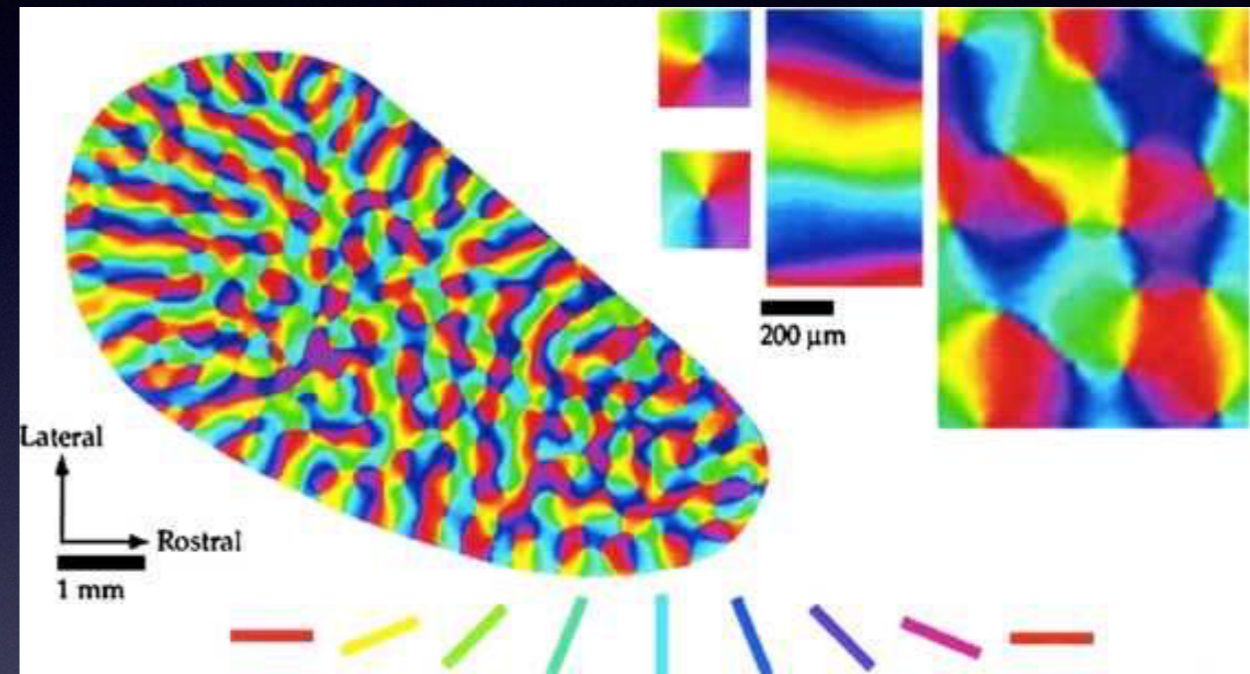
Orientation selectivity

Complex cell



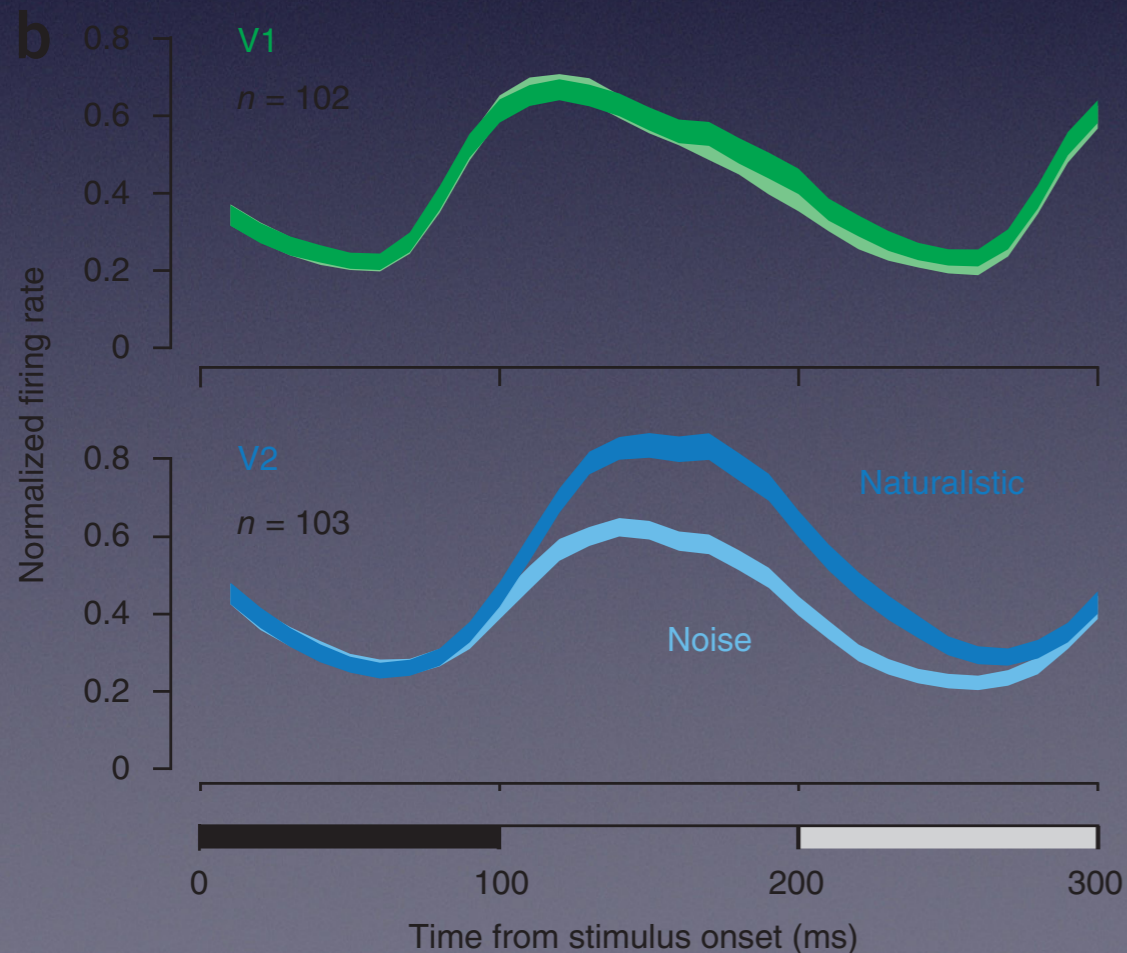
Orientation

Cells are **topographically mapped** according to their preferred pattern.

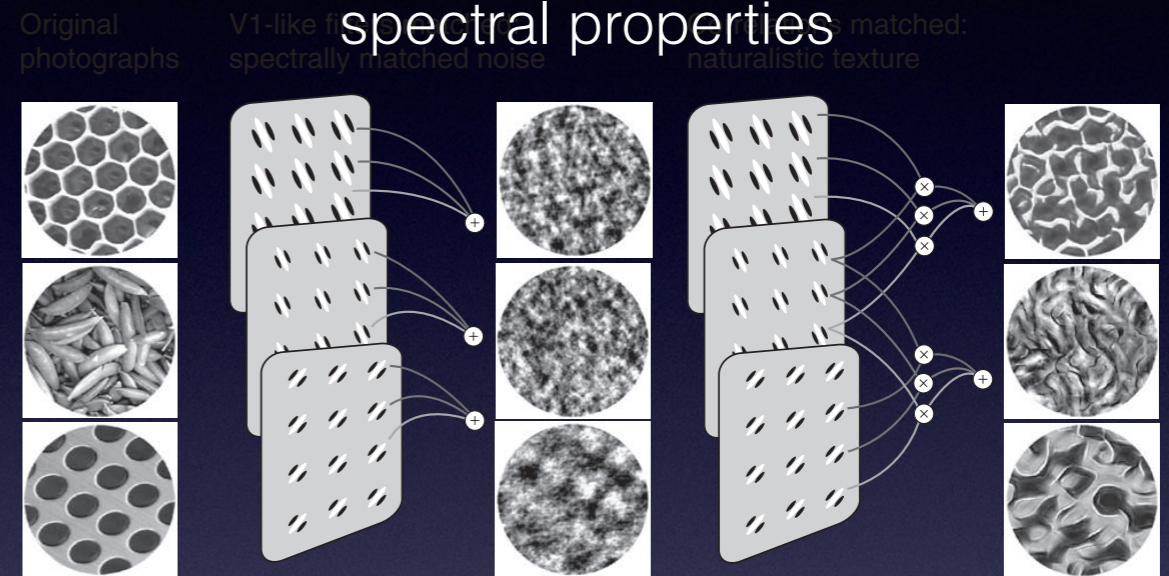


Primary Visual Cortex - V2

Area V2 (first cortical area after V1):



Noise images with matching spectral properties

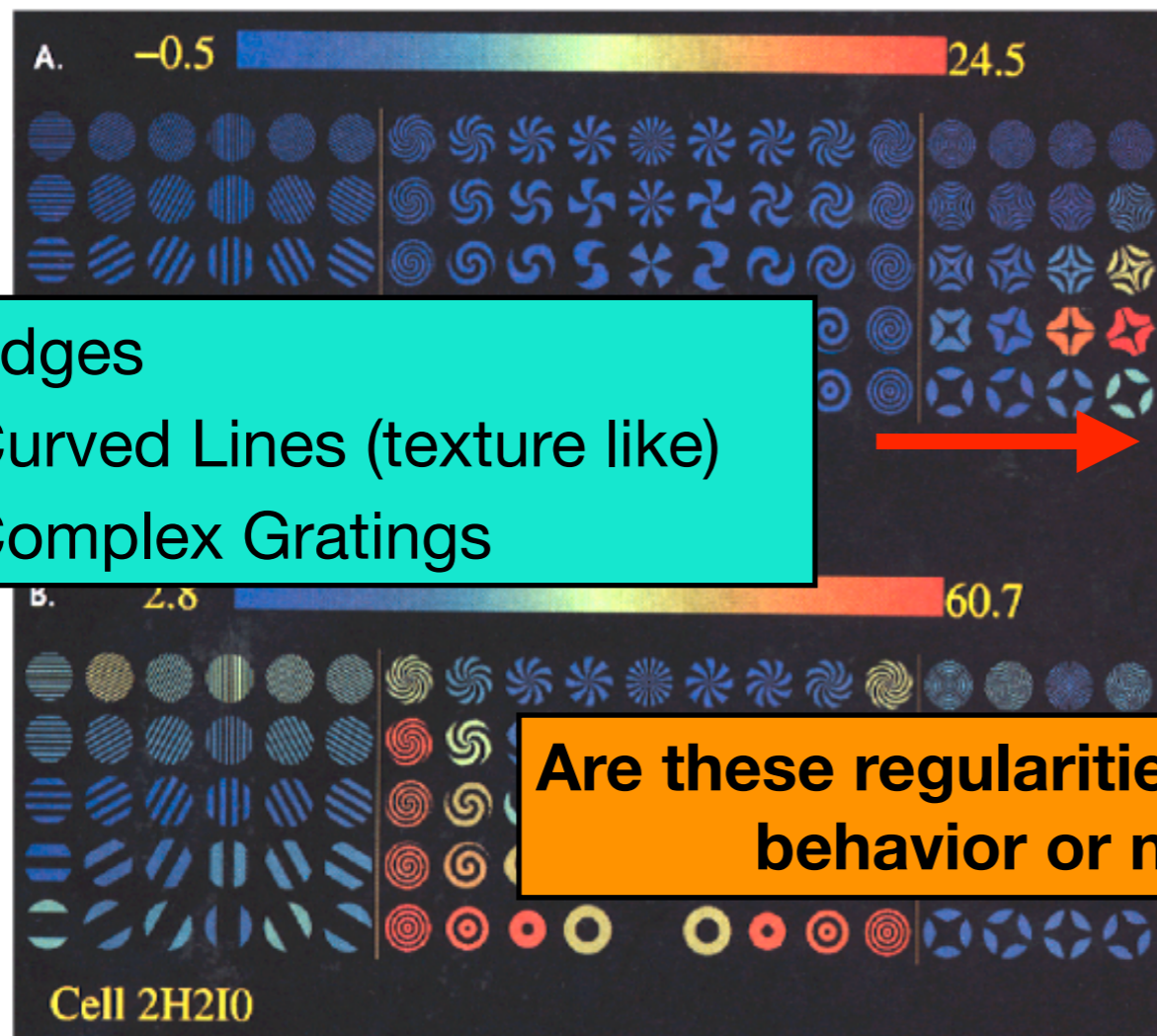


Interpretation:

- V2 neurons apply “and-like” operators on V1 outputs
- those “ands” are tuned toward natural co-occurring V1 statistics

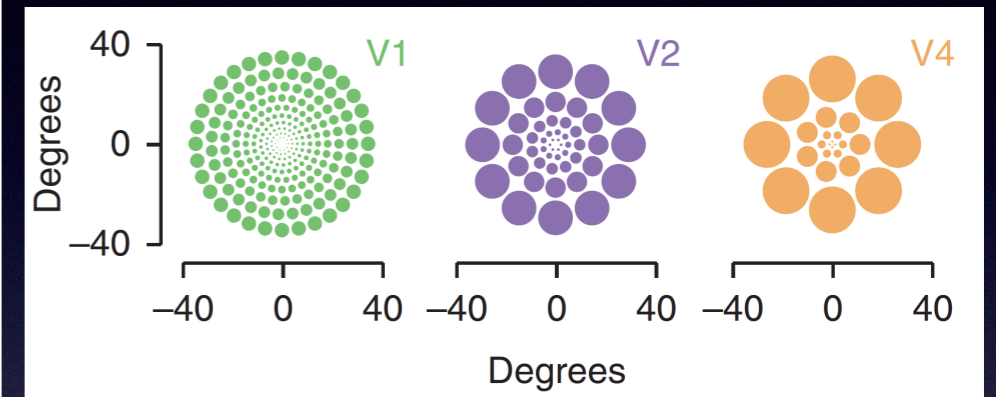
Primary Visual Cortex - V4

V4 Responses to Non-Cartesian Gratings
Gallant et al. 1996

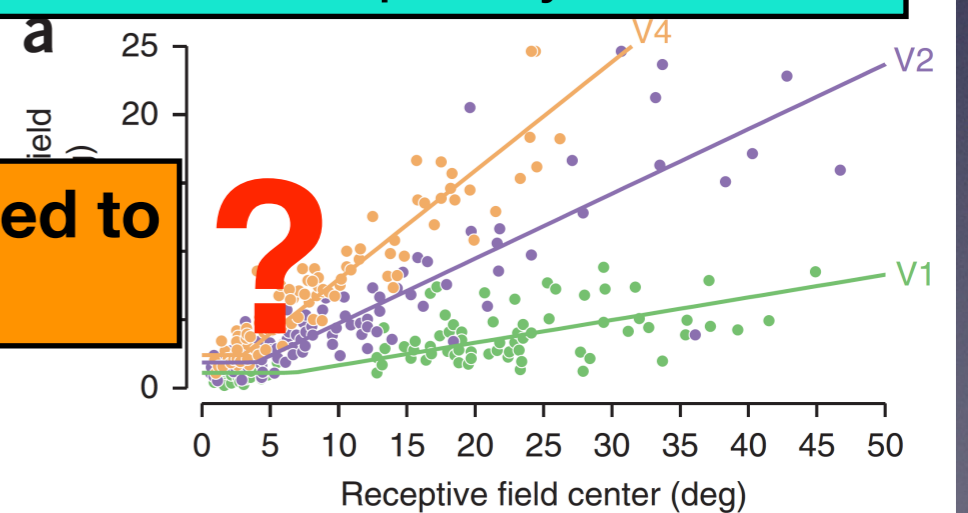


V1: Edges
V2: Curved Lines (texture like)
V4: Complex Gratings

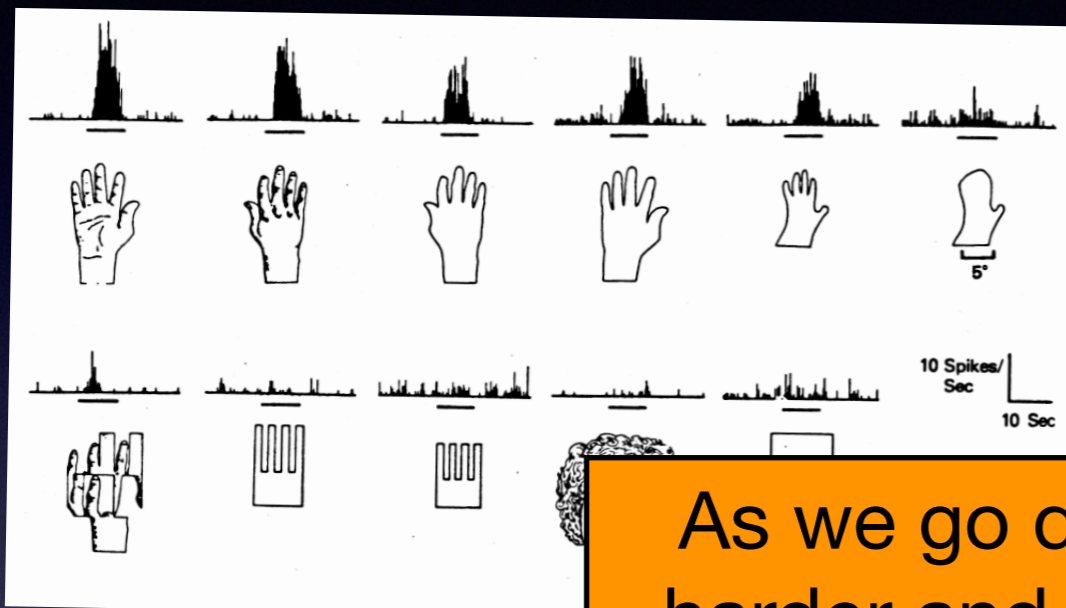
Are these regularities tuned to behavior or not?



Ventral Stream: Captures visual regularities of increasing complexity



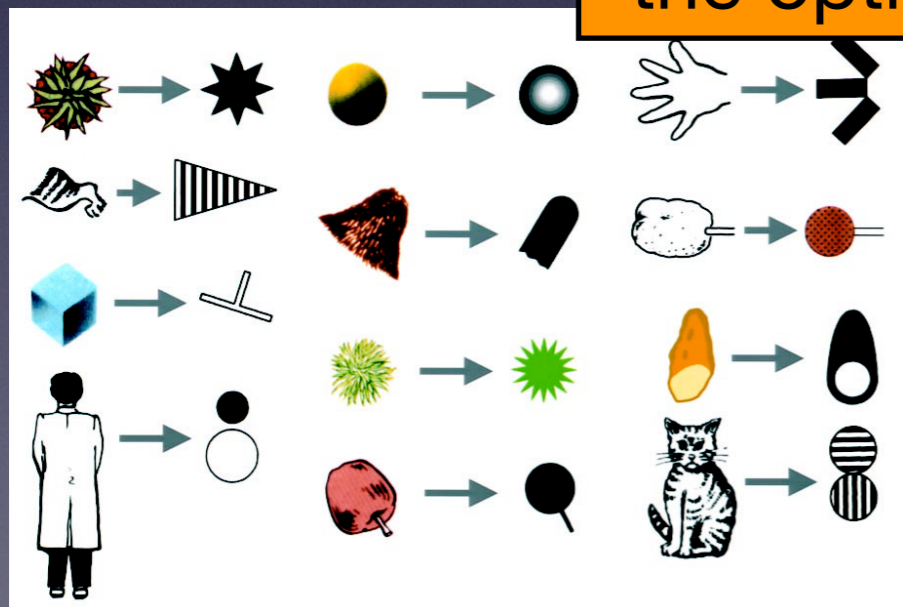
Primary Visual Cortex - IT



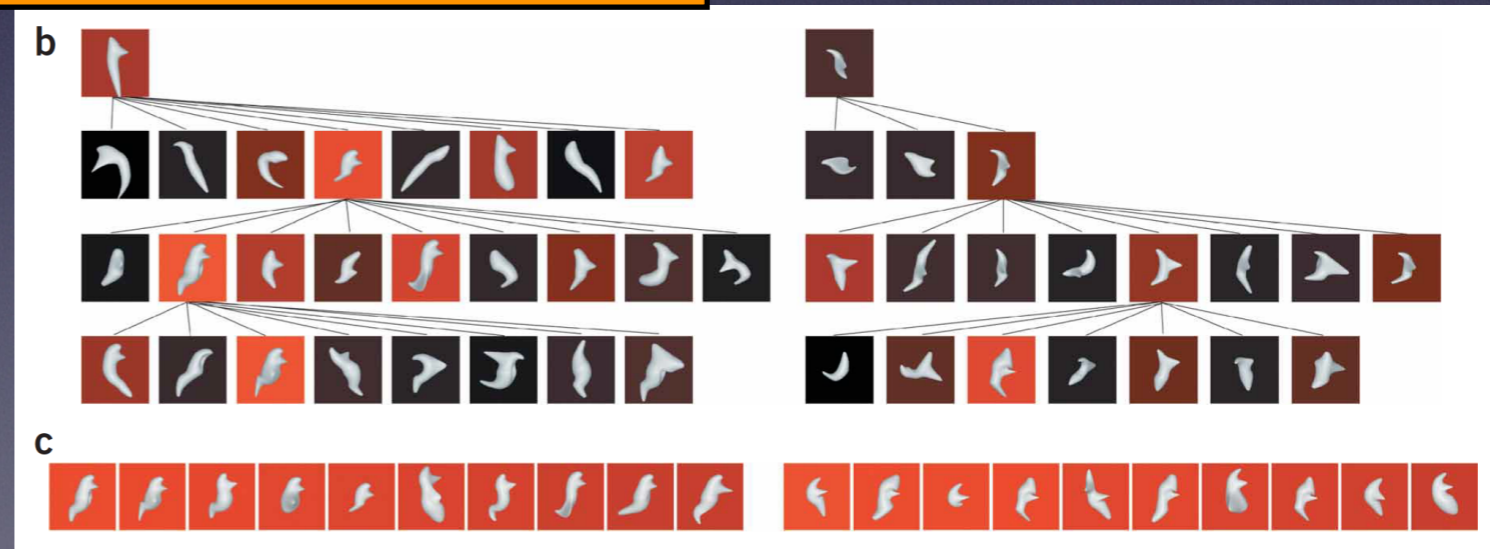
IT neurons can be tuned to specific combinations of features (high “selectivity”)

As we go deeper it becomes harder and harder to discover the optimal stimuli for neurons.

Adapted from Desimone et al. (1984)



Adapted from Tanaka



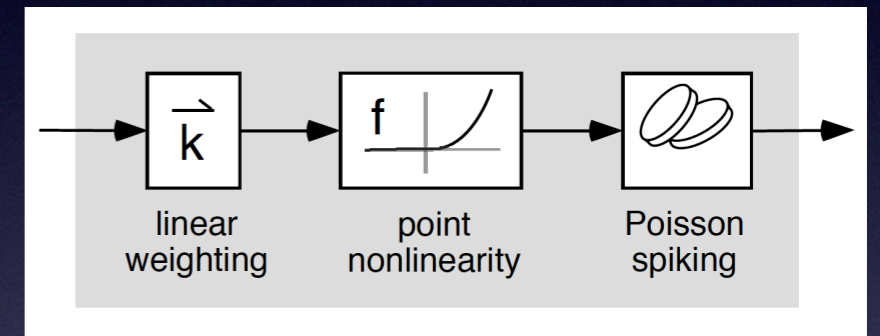
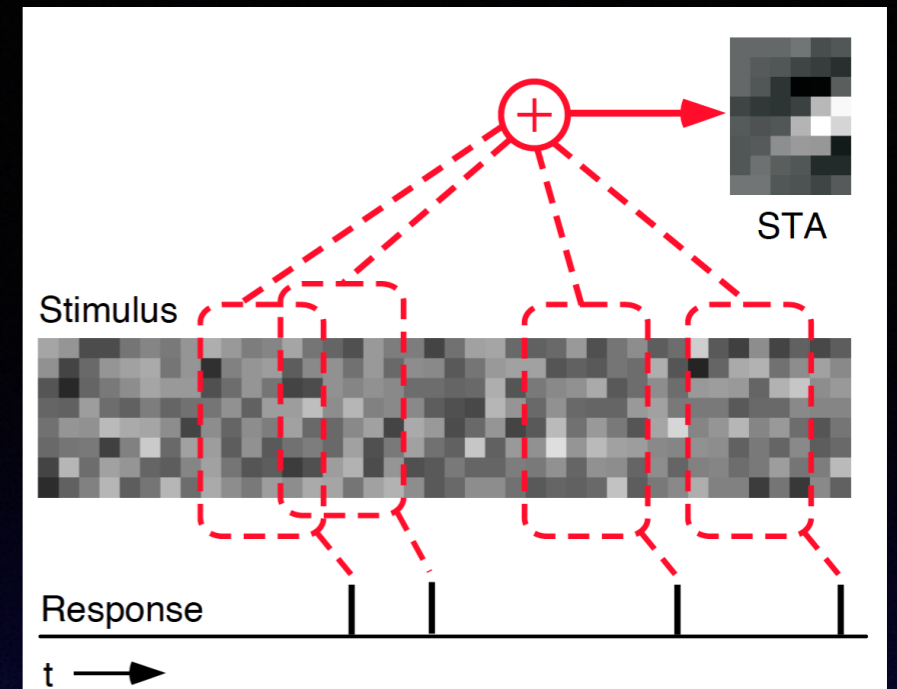
Adapted from Yamane, Connor Nature (2008)

Models of Vision

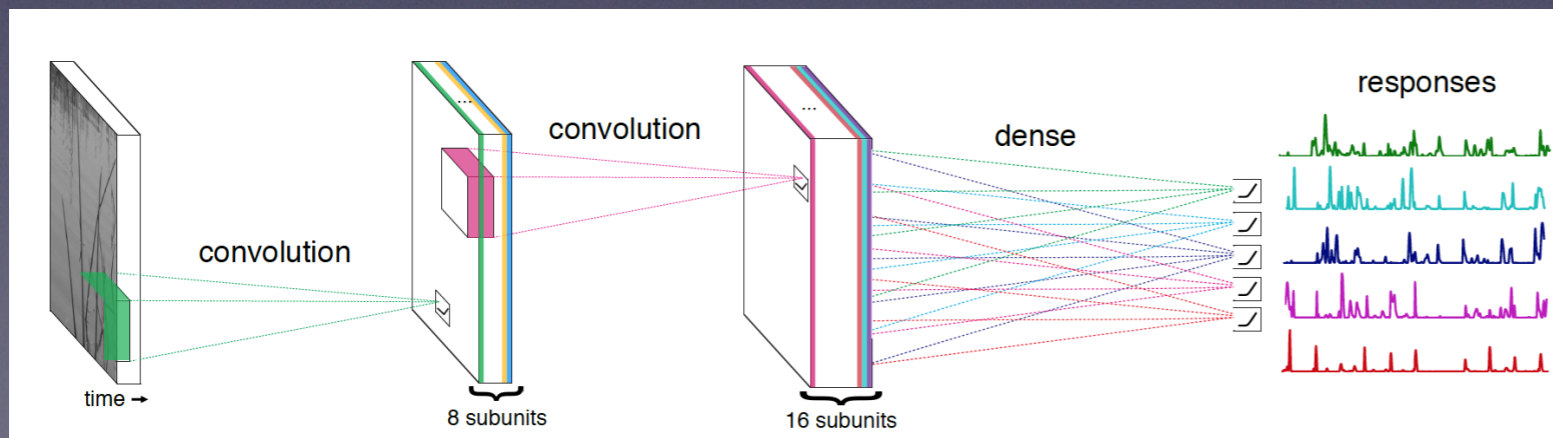
Vision Models

Retina

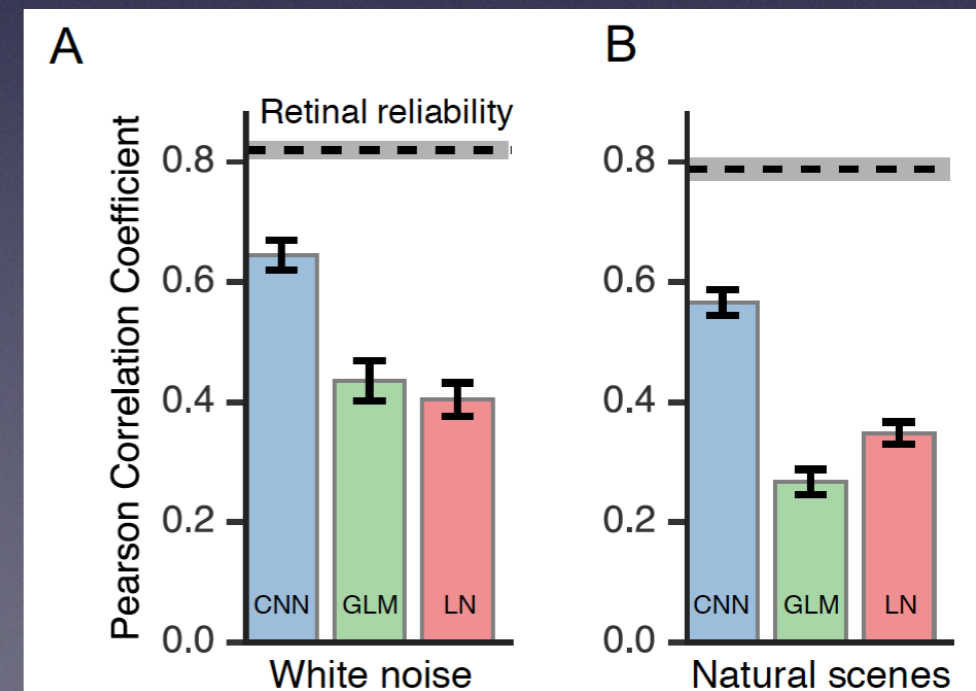
- Spike-Triggered Averaging (STA)
- Linear-Nonlinear Method (LN)
- Generalized Linear Models (GLM)
- Convolutional models (CNN)



Adapted from Simoncelli et al. (2004)

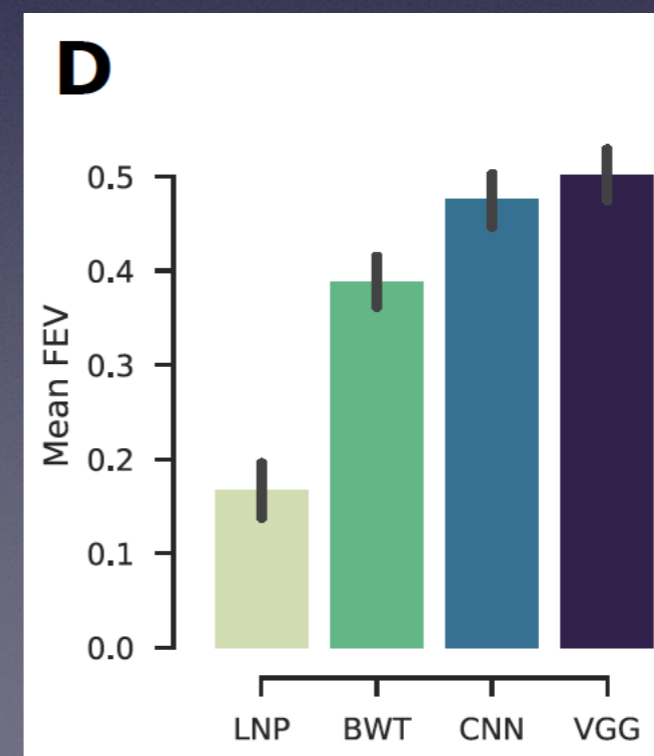
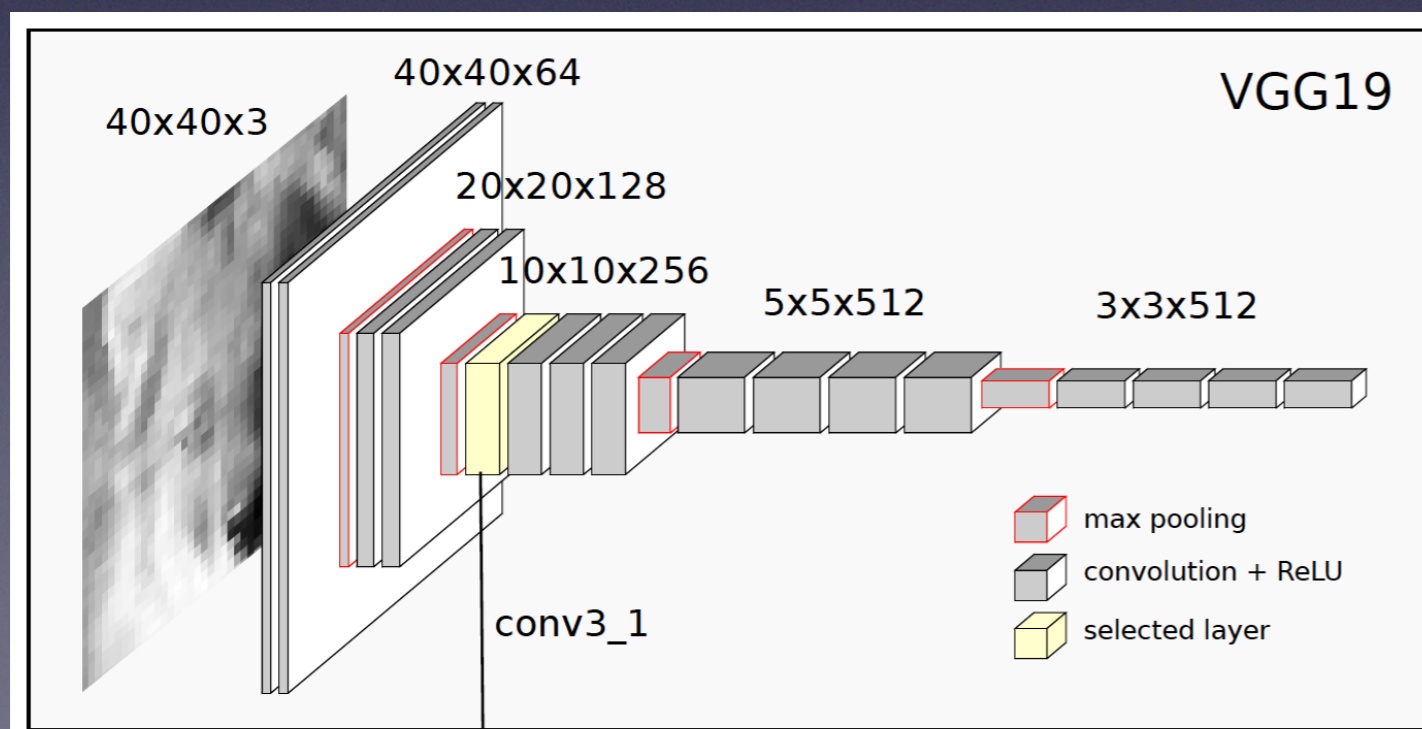
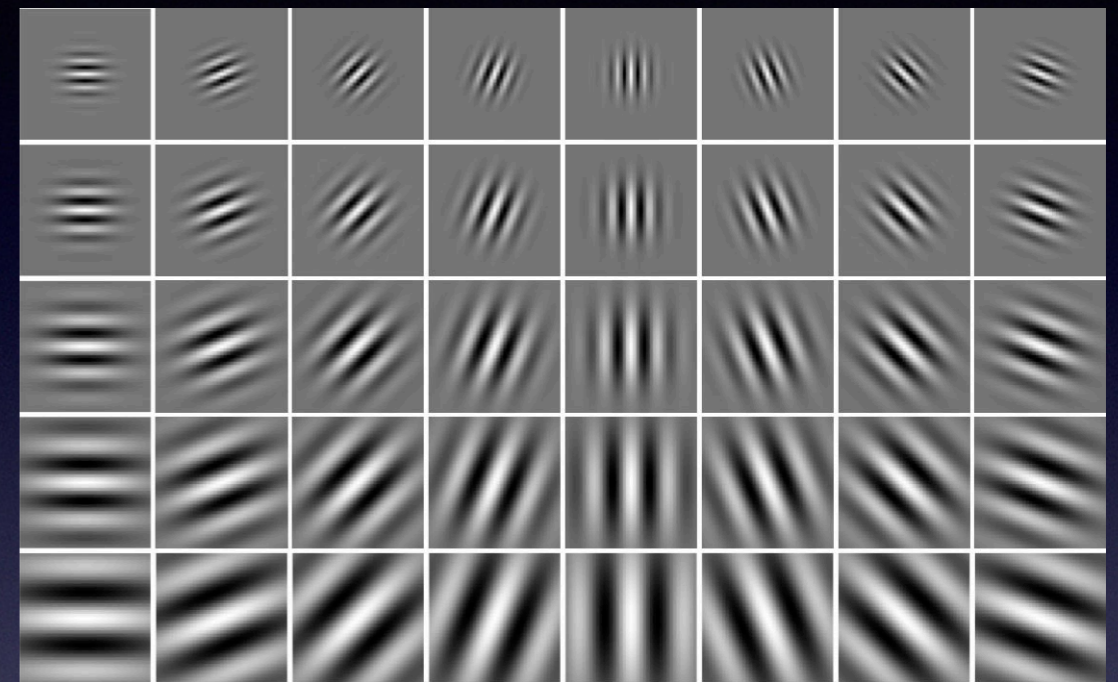


Adapted from McIntosh et al. (2017)



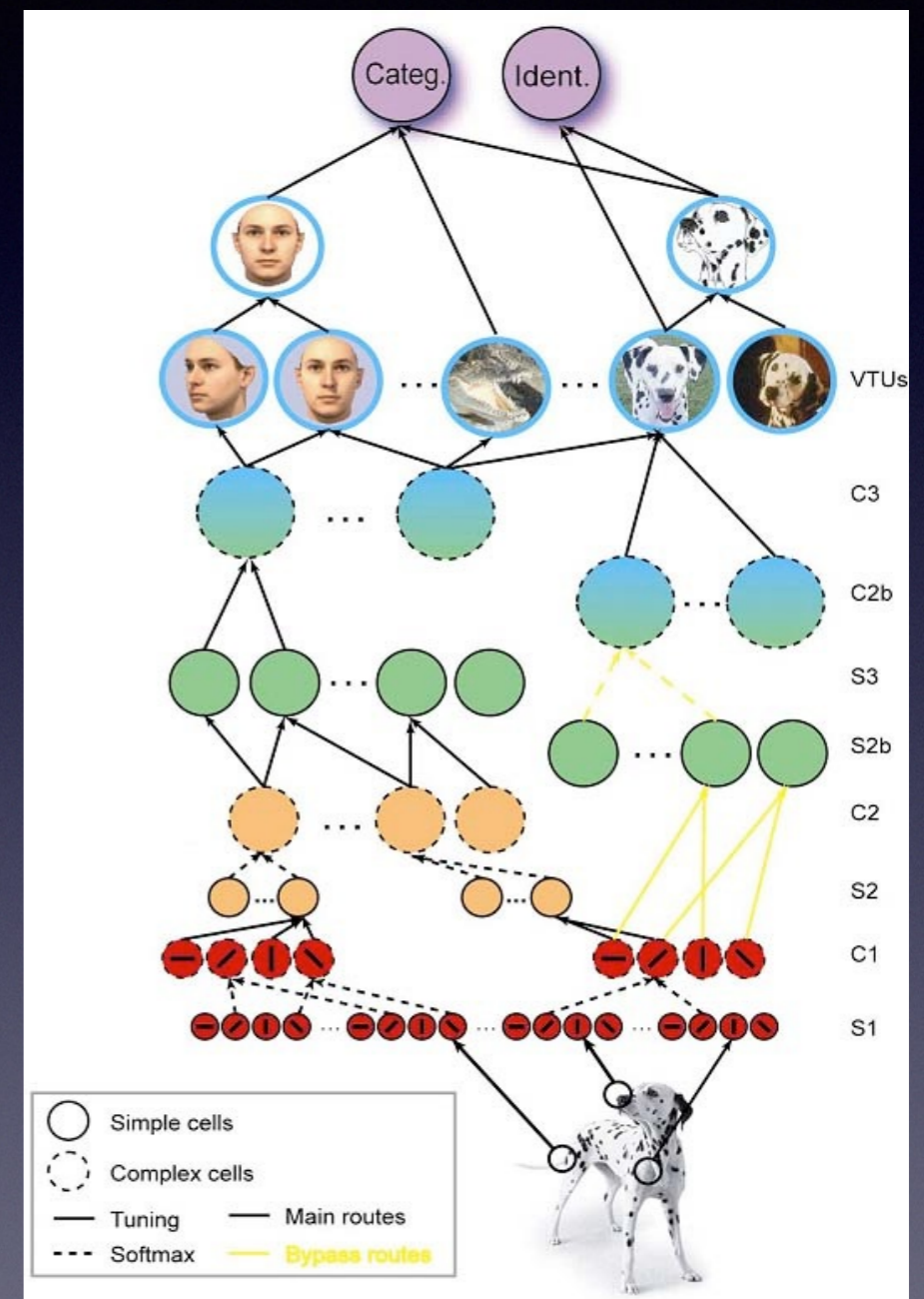
Vision Models - V1

- Gabor filter banks - Wavelet transforms
- LN-LN Cascade model
- CNNs



Vision Models - V2

- Hierarchy
- Spatially local filters
- Convolution
- Normalization
- ...

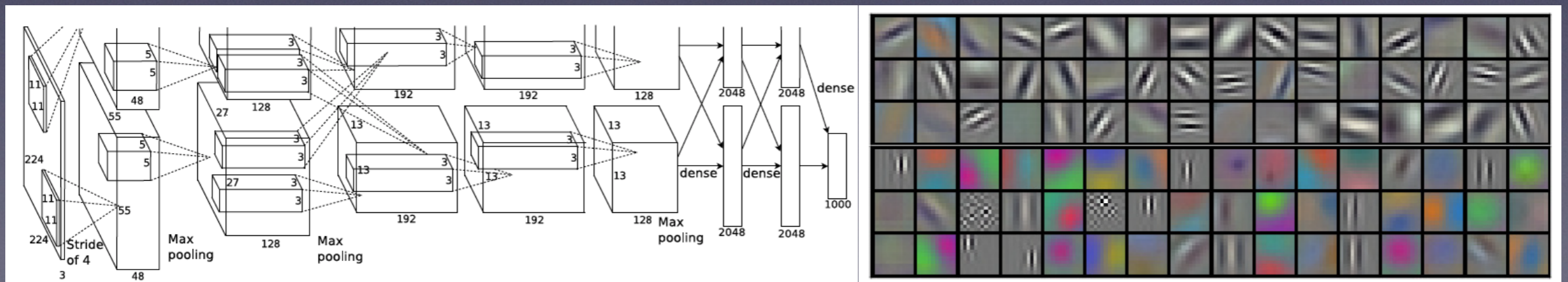


HMAX Model

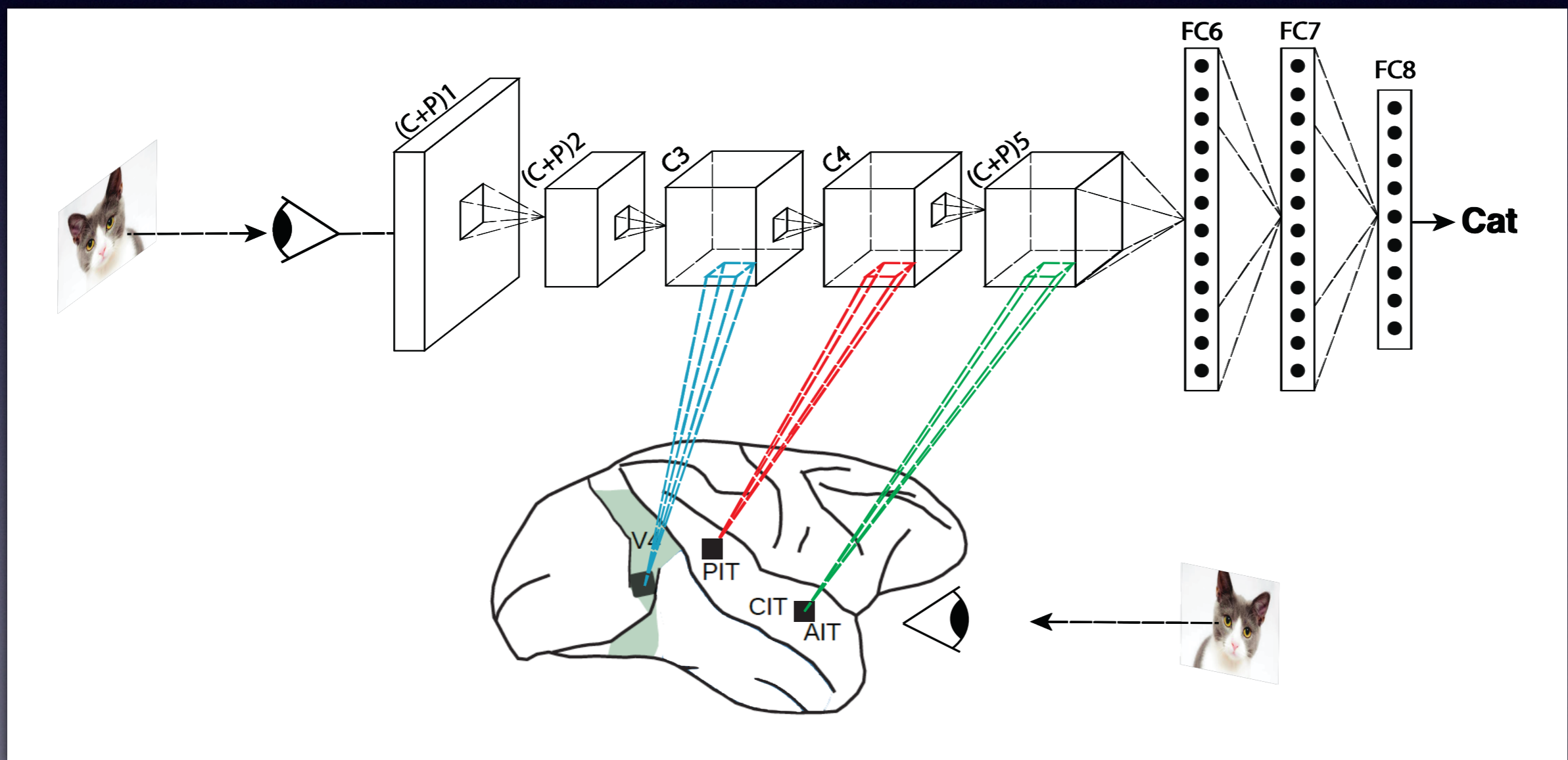
Serre, Kouh, Cadieu, Knoblich, Kreiman & Poggio 2005

Vision Models - CNNs

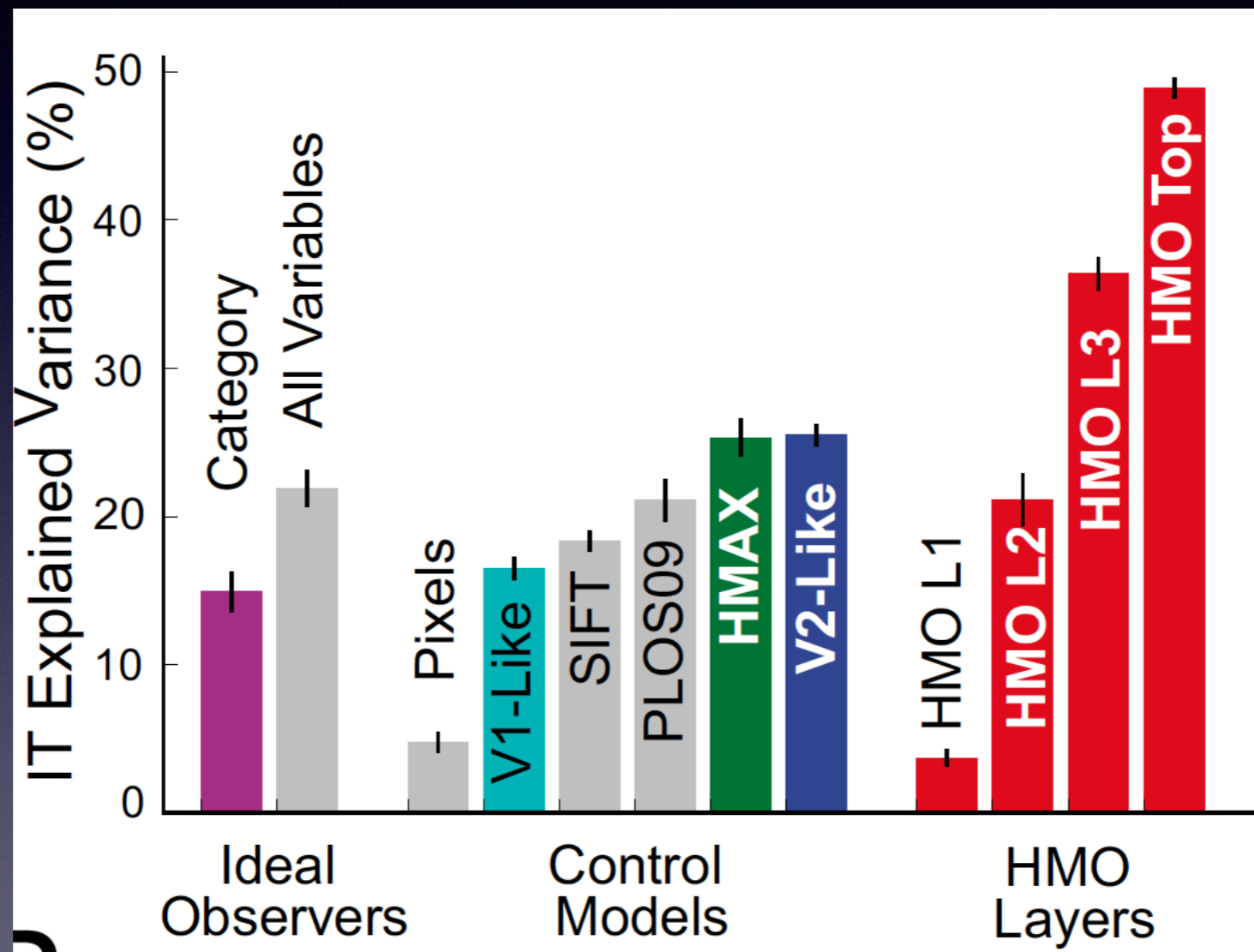
- Stack of Convolutions and Max-Pooling Layers with nonlinearities and normalization
- Parameters tuned on 1.28 M labeled images to minimize the error on object classification task.



Models of Higher Visual Areas CNNs



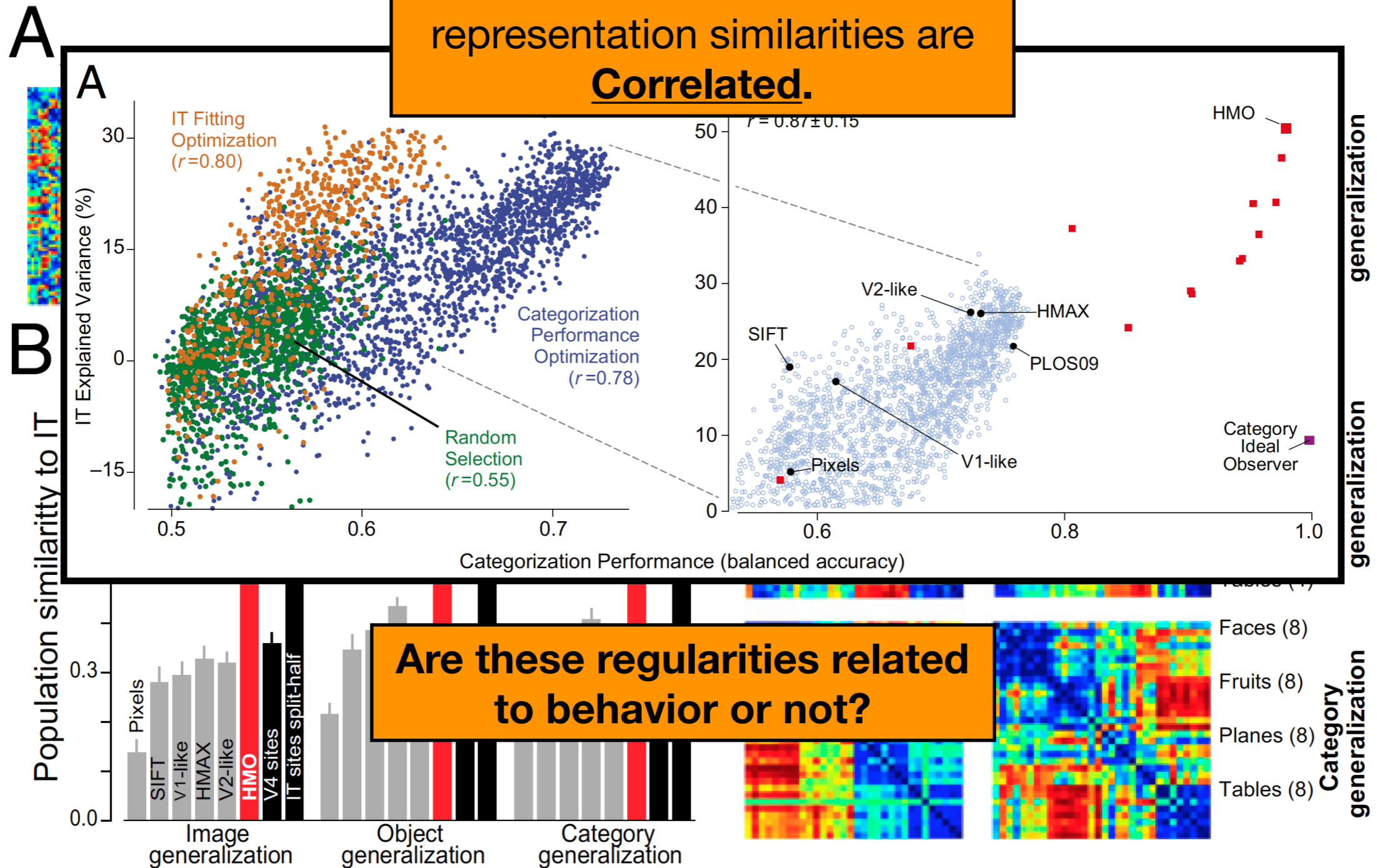
Vision Models - CNNs



Higher layers of CNNs explain **50-60%** of the explainable variance in IT neural activity.

Vision Models - CNNs

Behavioral performance and representation similarities are **Correlated.**



Applications-Automation

- Face recognition
- Self-driving Cars
- Security
- Many forms of intelligence...

What about in neuroscience?



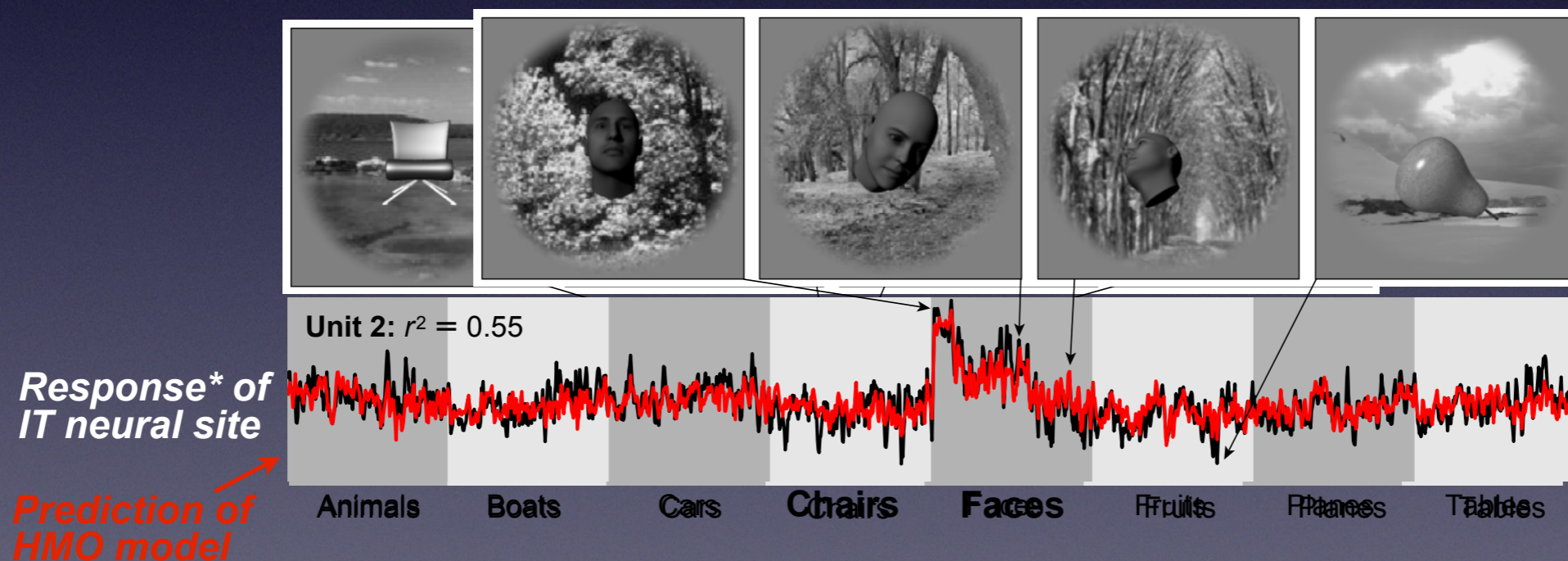
Vision is necessary to make sense of the visual world.

Neuroscience Applications

Prediction

Predictions of single site IT responses from layer 4 of HMO 1.0 model

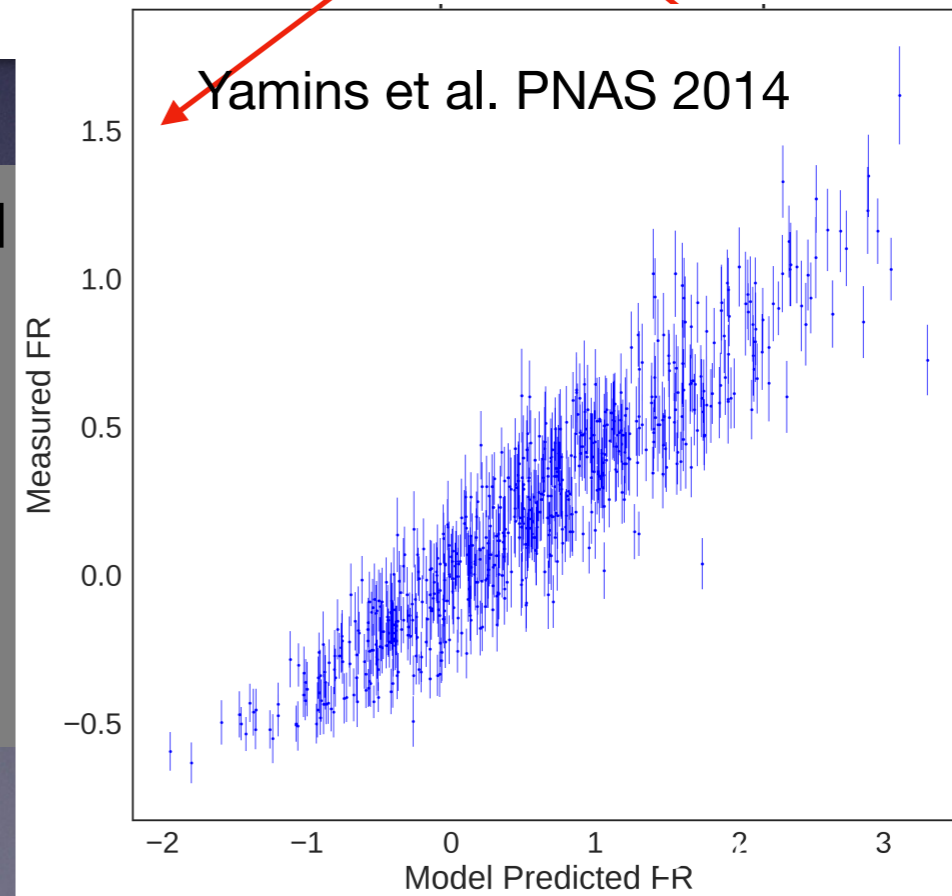
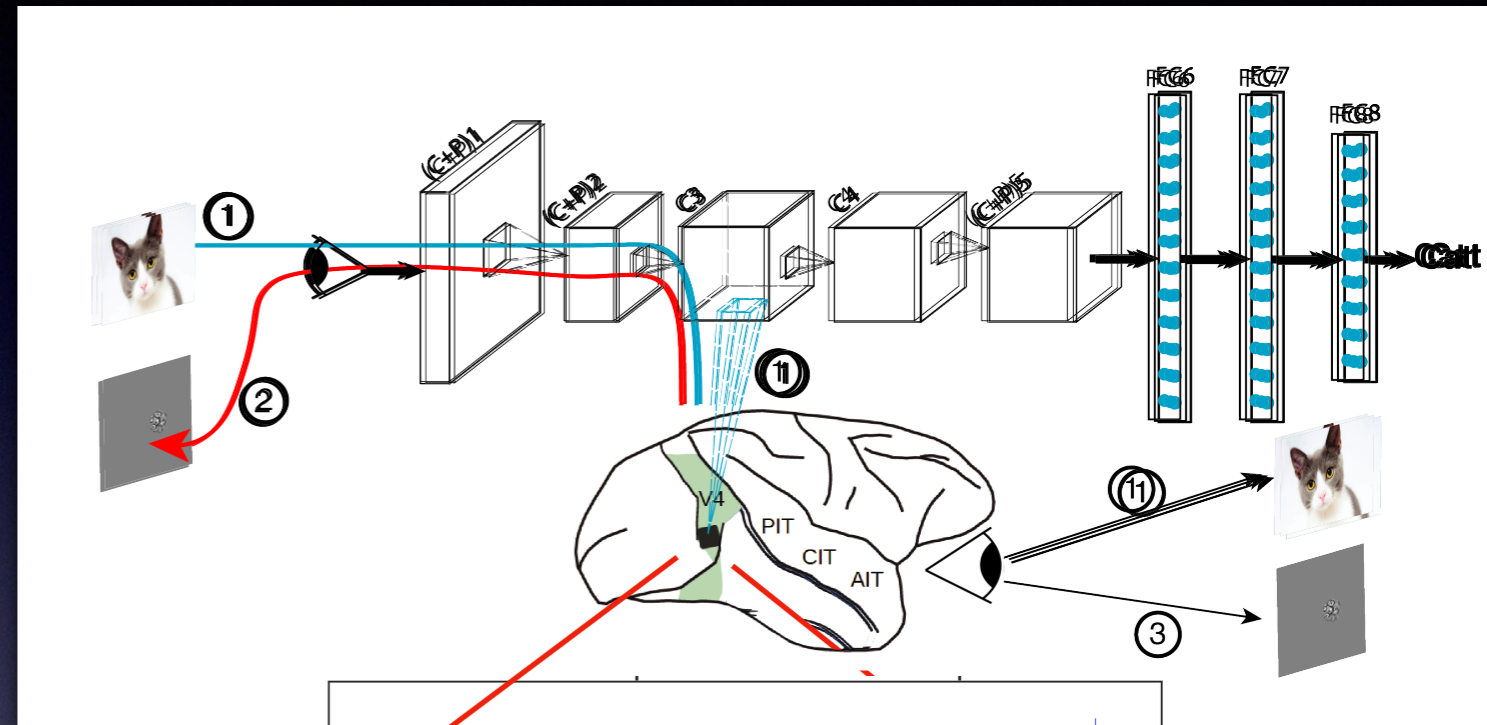
These are **predictions**: All of these objects and images were never previously seen by the HMO model



(* mean rate 70-170 ms after image onset)

Neuroscience Applications Control

- As a stronger model test, we here asked can we use a model to generate new visual images to drive a recorded neural population response into any desired state?
- We started with two specific goals:
 1. **“Maximal drive” (Stretch):** Drive any single neuron’s response beyond the maximum response observed thus far.
 2. **“One hot population” (OHP):** Drive any given neuron’s response up while holding the responses of all other (recorded) neurons at baseline (a test of independent control).

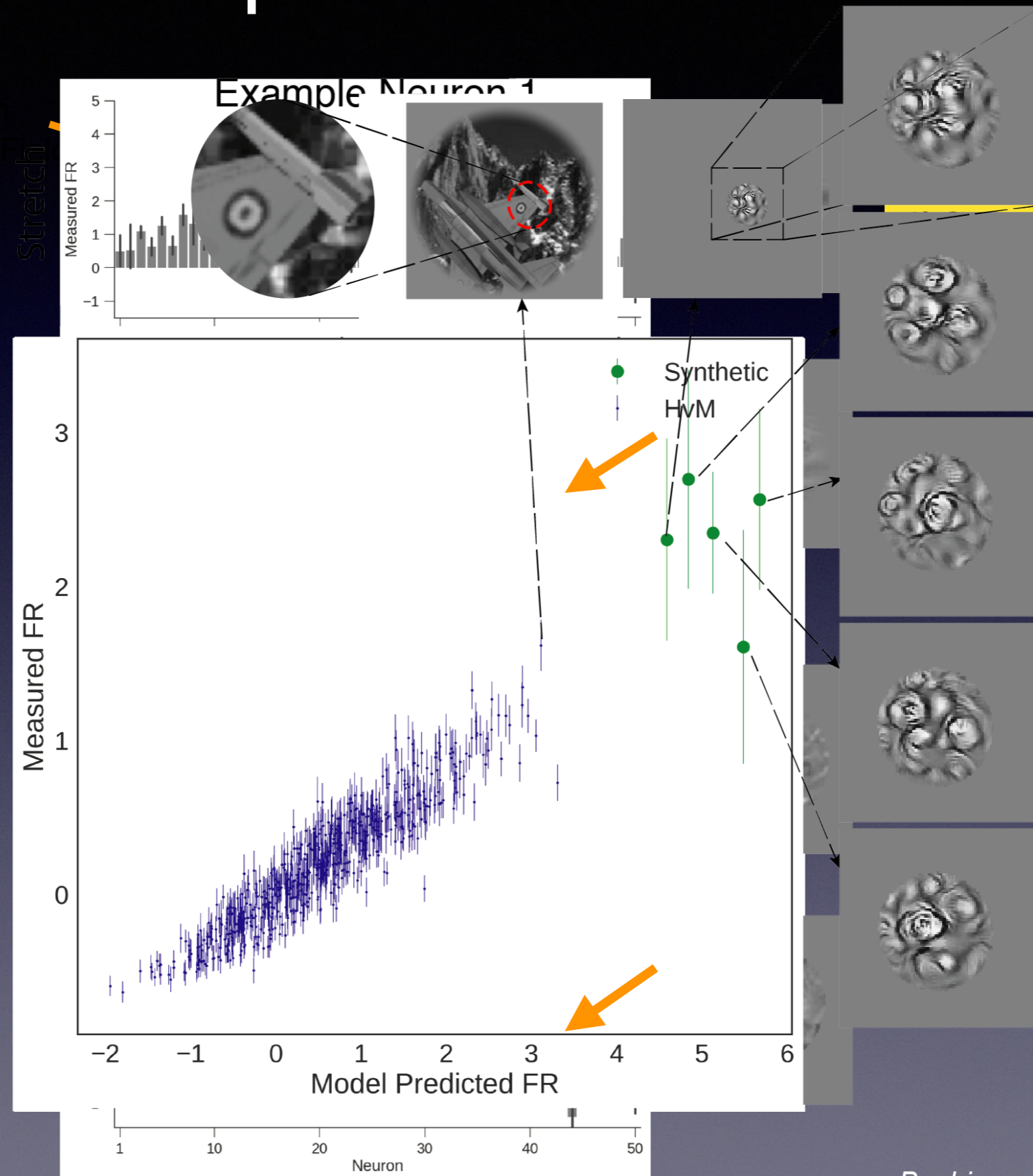


N1

iCarlo (in prep)

Neural Population Control

1) Stretch the firing rates beyond previously observed



Questions

“The only stupid question is the one that is never asked.”

Ramon Bautista